

# Satellite Soil Moisture Remote Sensing and Data Assimilation: Brief History & Current Status

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# OUTLINE

## 5. SM Data Research Plan

## 4. Soil Moisture Data Assimilation

## 3. MW Soil Moisture Retrievals

## 2. SM Observation Techniques

## 1. SM Data & Importance



# Soil Moisture Data & their Values

## ❖ **SM = Water held between soil particles:**

*Volumetric Soil Moisture (VSM) =  $[m^3 H_2O]/[m^3 Soil]$ , [%]; [-]*

*Gravimetric Soil Moisture (GSM) =  $[kg H_2O]/[kg Solid Soil]$ , [g/g]*

*Soil Wetness (SW) = VSM/Porosity*

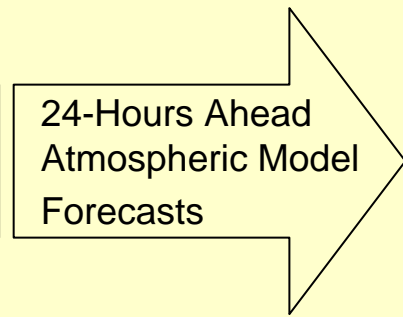
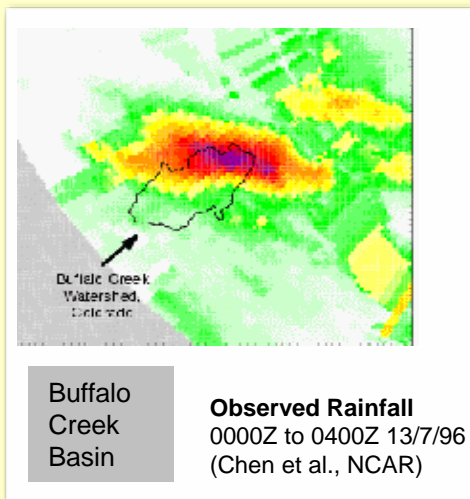


## ❖ **Soil moisture directly impacts agricultural productivity, military mobility, runoff potential/flood control/reservoir management, and for NOAA**

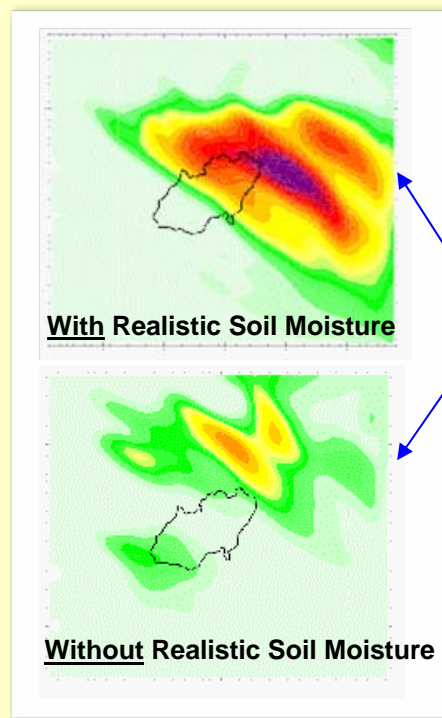


# Soil Moisture Impacts on Weather Forecasting (1)

Observed Rainfall from intense storm in Colorado:



Model forecasts with and w/o soil moisture:



**Actual storm event is forecasted accurately only if soil moisture information is available.**

## Soil Moisture Data Will Improve Numerical Weather Prediction (NWP) Over the Continents by Accurately Initializing Land Surface States

"The experience of the last ten years at ECMWF has shown the importance of soil moisture...Soil moisture is a major player on the quality of weather parameters such as precipitation, screen-level temperature and humidity and low-level clouds."

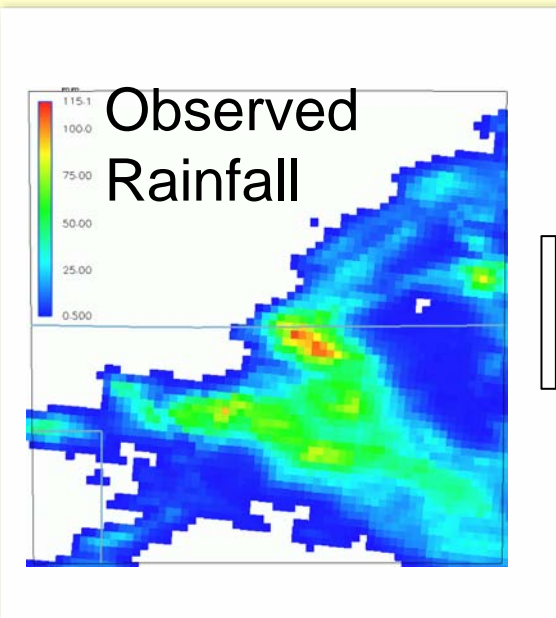
**Anthony Hollingworth, ECMWF**

"The strong motivation for this land data assimilation and land-monitoring space missions such as Hydros is that the land states of soil moisture, soil ice, snowpack, and vegetation exert a strong control on ...the heating and moistening of the lower atmosphere...forecast of tomorrow's heat index, precipitation, and severe thunderstorm likelihood."

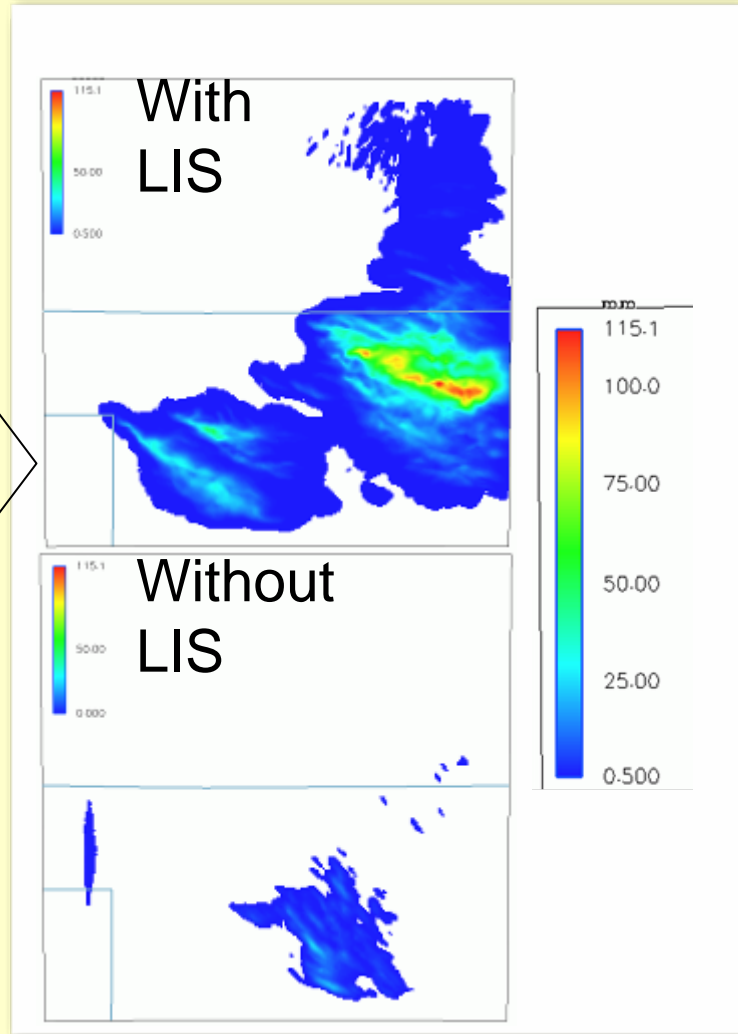
**Louis Uccellini, NCEP**

# Soil Moisture Impacts on Weather Forecasting (2)

## Soil Moisture Impact Example: WRF/LIS simulation for IHOP June 12, 2002



12-Hours Ahead  
Weather Forecasts



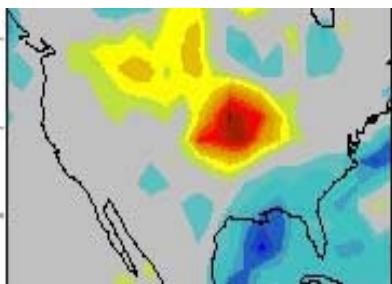
Forecast rainfall more accurate  
with LIS-initialized soil moisture

Peters-Lidard, et al, 2006

# Soil Moisture Impacts on Seasonal Predictability

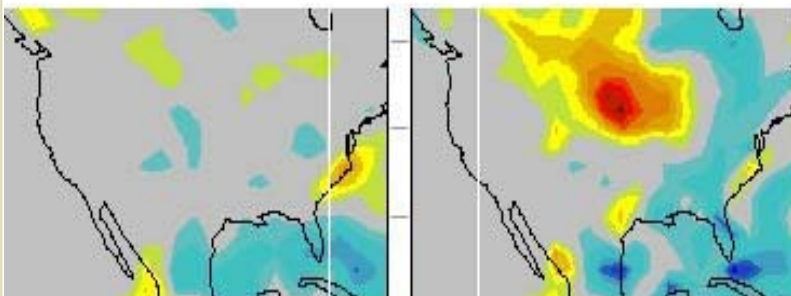
## Summer 1993 Rainfall Minus Summer 1988 Rainfall

Observations



Model driven by SSTs

Model driven by soil moisture and SSTs



Schubert et al. (2002)

Land-atmosphere coupling strength (JJA), averaged across AGCMs

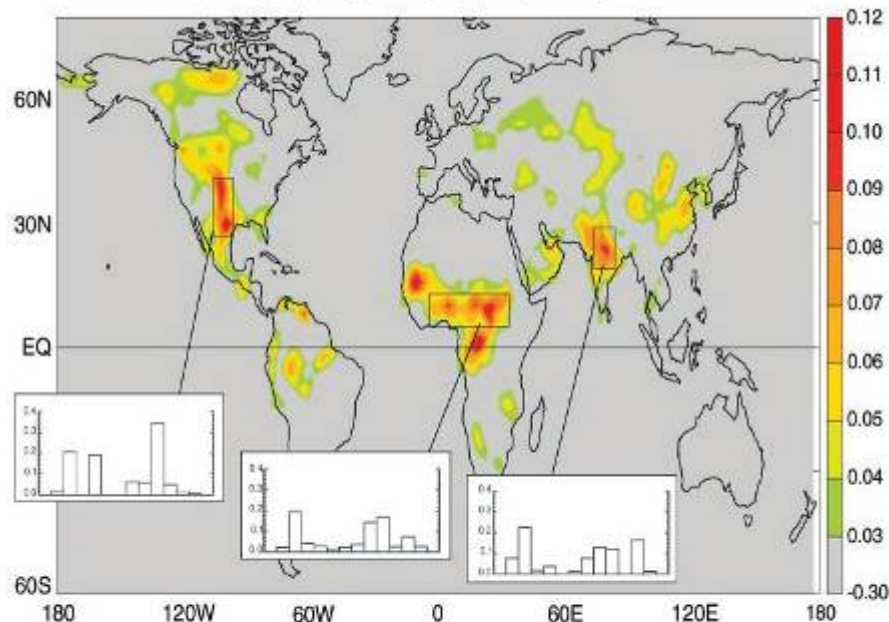


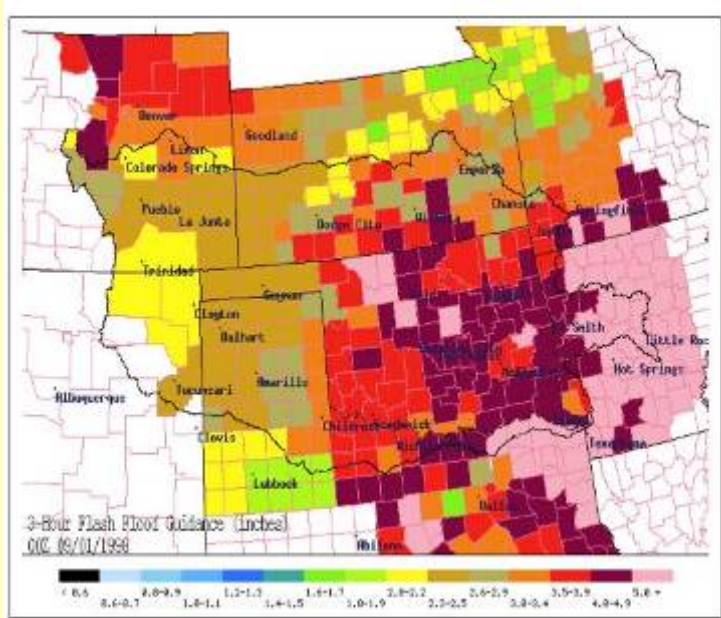
Fig. 1. The land-atmosphere coupling strength diagnostic for boreal summer (the  $\Omega$  difference, dimensionless, describing the impact of soil moisture on precipitation), averaged across the 12 models participating in GLACE. (Insets) Areal averaged coupling strengths for the 12 individual models over the outlined, representative hotspot regions. No signal appears in southern South America or at the southern tip of Africa.

Koster et al. (2004), *Science*, 305, 1138-1140.

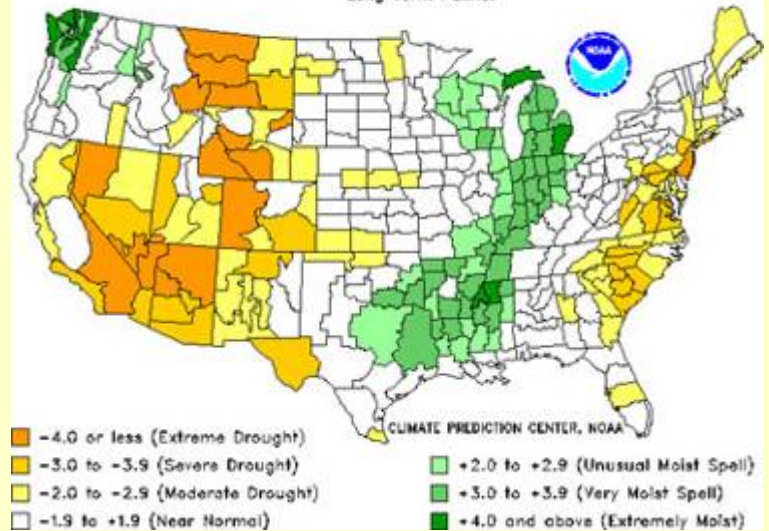
# Soil Moisture Data for Flood & Drought Monitoring



Current NWS Operational 30 km Flash Flood Guidance (FFG) is Based on *Model* Surface Soil Moisture Deficit



Drought Severity Index by Division  
Weekly Value for Period Ending 13 APR 2002  
Long Term Palmer



Current NOAA and National Drought Mitigation Center (NDMC) Operational Drought Index is also based on *Modeled* Soil Moisture Data.

**Soil moisture Observational data will replace model or proxy SM**

# Soil Moisture Observation Techniques

- ❖ **Soil Sampling** → *Point Data Collection*
  - ✓  $GSM = (W_{wet} - W_{dry})/W_{dry}$
  - ✓  $BD \text{ (Bulk Density)} = W_{dry}/Volume$
  - ✓  $VSM = GSM * BD$
  
- ❖ **Time Domain Reflectometer (TDR):** → *Point Data Collection*
  - ✓ *Theta probe, etc*
  
- ❖ **Microwave Radiometer/Radar:** → *Global/Regional Mapping*
  - ✓ *Ground-based: TMMR, GBMR, SLMR, etc*
  - ✓ *Air-borne: ESTAR, PBMR, PSR, etc*
  - ✓ *Satellite-borne: Skylab, SMMR, SSM/I, TMI, AMSR-E, WindSat, ESCAT, ASCAT, SMOS, Aquarius, and GPM? Hydros? MIS?*



## ❖ **Scientific Basis:**

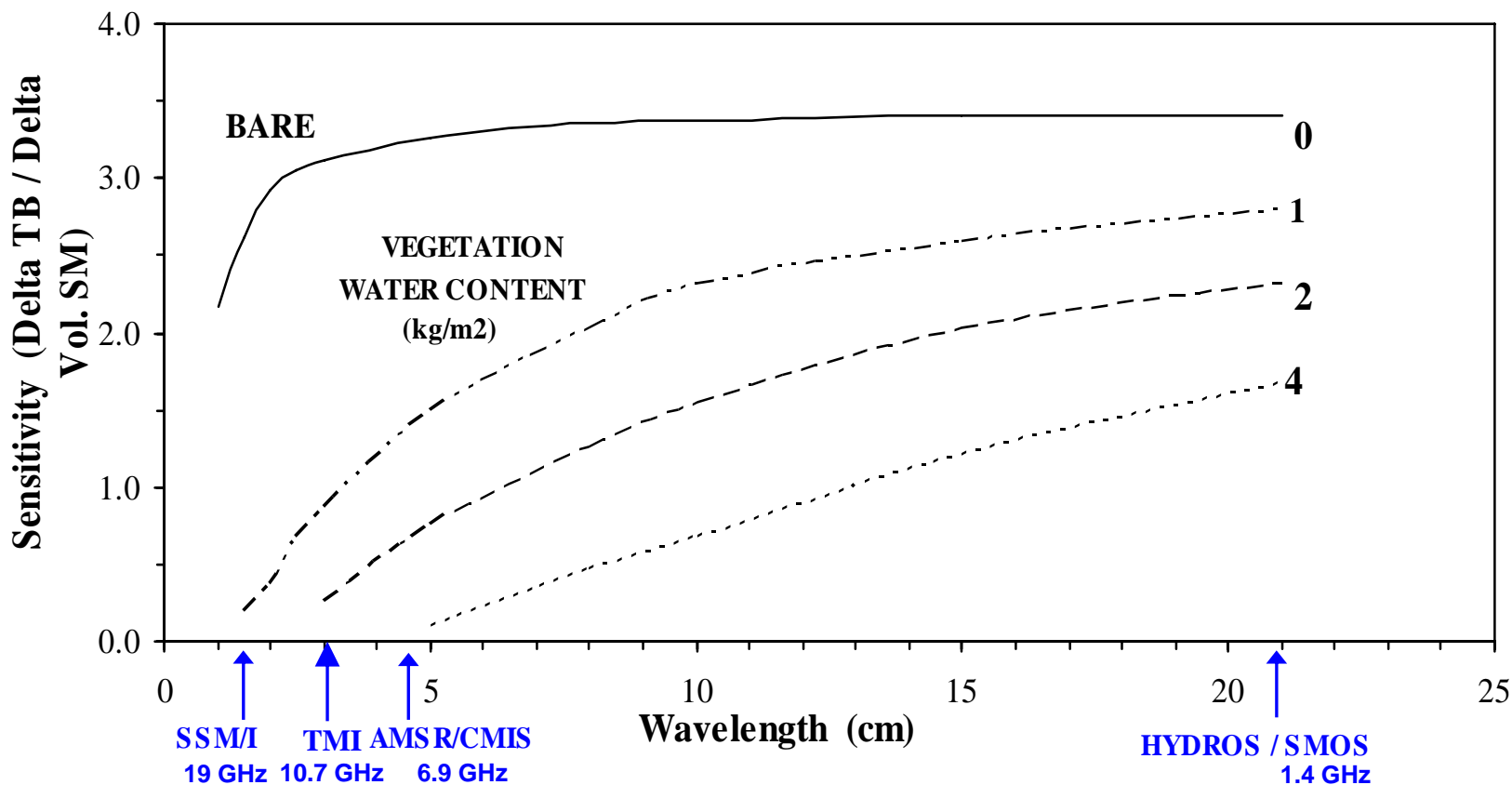
- ✓ **Dielectric constants:**  $\epsilon_{\text{water}} = \sim 80$ ,  $\epsilon_{\text{dry\_soil}} < 4$ ,  $\rightarrow \epsilon_{\text{wet\_soil}} = 4 - 80$ ;
- ✓ **Fresnel equation: reflectivity**  $\leftrightarrow \epsilon_{\text{wet\_soil}} \rightarrow \sigma = f(\text{SM, etc, etc})$ ;
- ✓ **emissivity = 1 – reflectivity,**  $\rightarrow T_B = g(\text{SM, etc}).$

## ❖ **Brief Research History (Passive Radiometry):**

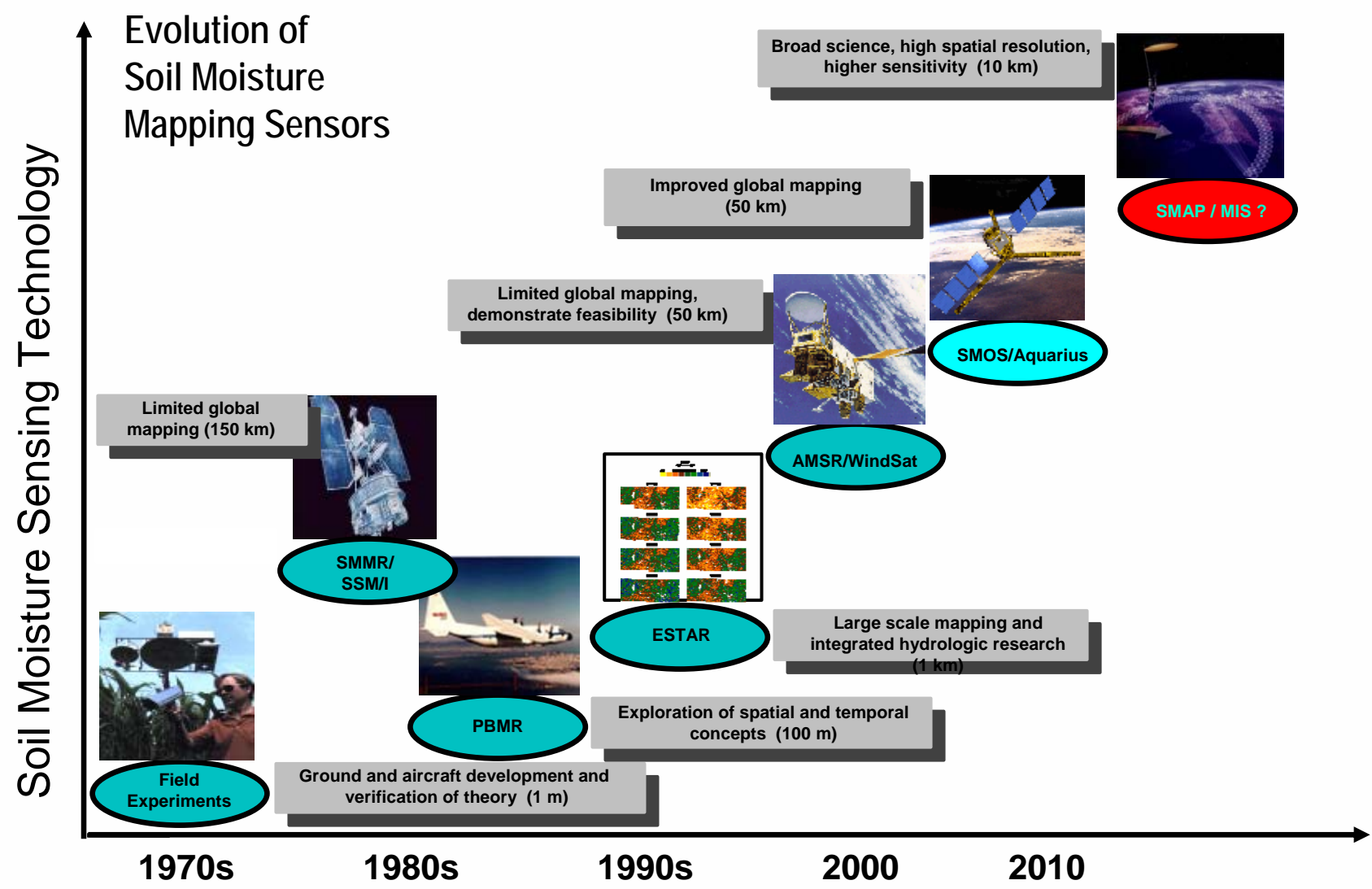
- ✓ **1930s-1950s:** MW “upward” radiometer used to measure EM energy of extraterrestrial origin.
- ✓ **Straiton et al (1958):** 1<sup>st</sup> radiometer pointing “downward” for terrestrial observations.
- ✓ **Blinn & Quade (1973), Schmugge et al (1974, 1977), England (1975), Ulaby et al (1975), Njoku & Kong (1977), Eagleman & Lin (1976), Schmugge (1978):** 1<sup>st</sup> radiometers for soil moisture remote sensing.
- ✓ **Choudhury et al (1979), Schmugge (1980), Wang & Schmugge (1980), Dobson & Ulaby (1981), Jackson et al (1982), Mo et al (1982), Shutko et al (1982), Dobson et al (1984, 1985), Wang (1985):** 1<sup>st</sup> studies accounting impacts of roughness, soil texture, vegetation canopy, skin temperature and SM itself on the SM-TB relationships.
- ✓ **Jackson (1993), Jackson (1997), Njoku & Li (1999), Owe et al (2001), and others:** development, refinement, and validation of regional or global soil moisture retrieval algorithms.



## Microwave Sensitivity By Wavelength and Vegetation Density



# MW Soil Moisture Remote Sensing Technology



# Microwave Soil Moisture Sensors Details (1)

- ❖ The Scanning Multichannel Microwave Radiometer (**SMMR**): launched with Nimbus-7 in **1978** and stopped in **1987**; was measuring TBs at **6.63**, **10.69**, **18.0**, 21.0 and 37.0 GHz frequencies. Own et al (2001) created a SM product.
- ❖ The Special Sensor Microwave Imager (**SSM/I**) is a passive microwave radiometer flown aboard Defense Meteorological Satellite Program (DMSP) satellites since **1987**: DMSP F-8, 10, 11,12,13,14,15. SSMI/S on F-16 follows. A Global Soil Wetness Index product has been created by Bob Kuligowski.

Frequency (GHz)	Polarization	Integration Period	3 dB Footprint Size	
			Along-track	Cross-track
19.35	vertical	7.95 ms	69 km	43 km
19.35	horizontal	7.95 ms	69 km	43 km
22.235	vertical	7.95 ms	50 km	40 km
37.0	vertical	7.95 ms	37 km	28 km
37.0	horizontal	7.95 ms	37 km	29 km
85.5	vertical	3.89 ms	15 km	13 km
85.5	horizontal	3.89 ms	15 km	13 km

- ❖ The Tropical Rainfall Measurement Mission (TRMM) Microwave Imager (**TMI**) observes the 35N-35S latitude zone at five separate frequencies since **1997**: **10.7**, **19.4**, 21.3, 37, 85.5 GHz. Bindlish & Jackson (2003) has created a global tropical area soil moisture data product.

# Microwave Soil Moisture Sensors Details (2)

- ❖ **AMSR-E** is Japan's Advanced Microwave Scanning Radiometer for NASA's Earth Observing System. It's onboard the Aqua satellite of EOS that was successfully launched in May 2002. A global Soil moisture has been created by Njoku et al (2003) since 2002.

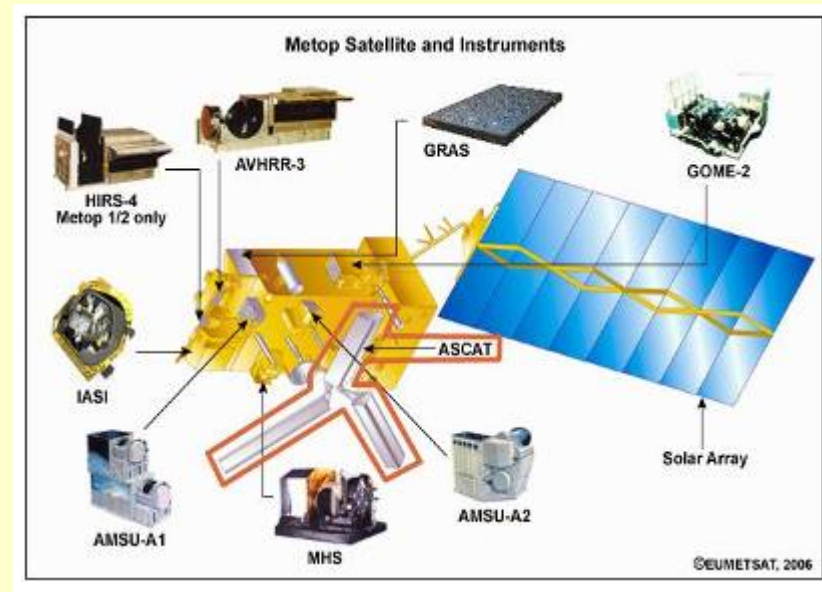
Observation Frequency	6.925 GHz	10.65 GHz	18.7 GHz	23.8 GHz	36.5 GHz	89.0 GHz	
						A	B
Spatial Resolution	50 km		25 km		15 km	5 km	
Band Width	350 MHz	100 MHz	200 MHz	400 MHz	1000 MHz	3000 MHz	
Polarization	Horizontal and Vertical						
Incident Angle	55°					54.5°	
Cross polarization	less than -20 dB						
Swath Width	more than 1,450 km						

- ❖ **WindSat/Coriolis** is another MW radiometer successfully launched by Naval Research Lab (NRL) primarily for ocean wind and SST in Jan. 2003. It has C- and X-band observations similar to AMSR-E and can be used to derive global soil moisture products.

Freq, GHz	Channels	BW, MHz	EIA, deg	IFOV, km
6.8	v, h	125	53.5	40x60
10.7	v, h, ±45, lc, rc	300	49.9	25x38
18.7	v, h, ±45, lc, rc	750	55.3	16x27
23.8	v, h	500	53.0	12x20
37.0	v, h, ±45, lc, rc	2000	53.0	8x13

# Microwave Soil Moisture Sensors Details (3)

- ❖ **ESCAT-1/2** are C-band (5.3GHz) scatterometer flown onboard ERS-1 (1991-1996) and ERS-2 (1995-present). **ASCAT** is the advanced scatterometer flown on MetOP-A since Oct. 2006. Intensive researches have been done at Vienna University of Technology in Austria to derive a global soil moisture data set from these scatterometers' observations (Wagner et al, 2003).



- ❖ The synthetic aperture radars (**SAR**) on ERS-1/2 (1991-present) and the advanced SAR (**ASAR**) onboard ENVISAT (2002-present) are providing high spatial resolution backscatter observations which can also be used to derive soil moisture. However, further research is needed to derive operational soil moisture data products from the radar observations.

- ❖ **European Space Agency (ESA)** has planned a **Soil Moisture and Ocean Salinity (SMOS)** mission to specifically observation global soil moisture using L-band MW radiometry. The satellite will be launched in 2008.
- ❖ United States planned a **Hydrospheric States (Hydros)** mission to specifically observation global soil moisture using both L-band MW radiometer and radar, but cancelled the mission in later 2005.
- ❖ United States also planned the **Conical Scanning Microwave Imager/ Sounder (CMIS)** for NPOESS, and cancelled the instrument in 2006.
- ❖ NASA's decadal survey on Earth Science and Applications from Space listed a soil moisture active-passive mission (**SMAP**) as one of four missions recommended to NASA for year 2010-2013 time frame.



- ❖ **Evaluation of NASA's Current AMSR-E Soil Moisture Data Product**
- ❖ *An Alternative AMSR-E Soil Moisture Data Product from NOAA-USDA*
- ❖ *Retrieving High Resolution Soil Moisture From Hydros*



- ✓ *NASA's newest satellite observational data product of global land surface soil moisture.*
- ✓ *Acquired (almost) continuously since June 18, 2002.*
- ✓ *Spatial resample resolution is 25km by 25km and available for most land areas once every 2-3 days.*
- ✓ *Generated from the polarization ratios of AMSR-E 10.7 and 18.7GHz channels with footprint sizes of these channels being about 21km to 38km.*

- ✓ *NASA GSFC and partners have developed the North America Land Data Assimilation System (NLDAS) and Global Land Data Assimilation System (GLDAS) that can output soil moisture simulations of various land surface models (e.g. Mosaic, Noah, CLM, ...);*
- ✓ *NLDAS Mosaic soil moisture data for the years since 1996 have been available at the website <http://ldas.gsfc.nasa.gov>*
- ✓ *Through the enhanced version of LDAS software system (LIS), LDAS LSMs can be run at many spatial resolution (e.g., 0.25 lat/long matching AMSR-E soil moisture data product)*
- ✓ *The NLDAS atmospheric forcing data sets (Cosgrove et al, 2003) are used to simulate soil moisture with Mosaic and Noah LSMs for this study.*



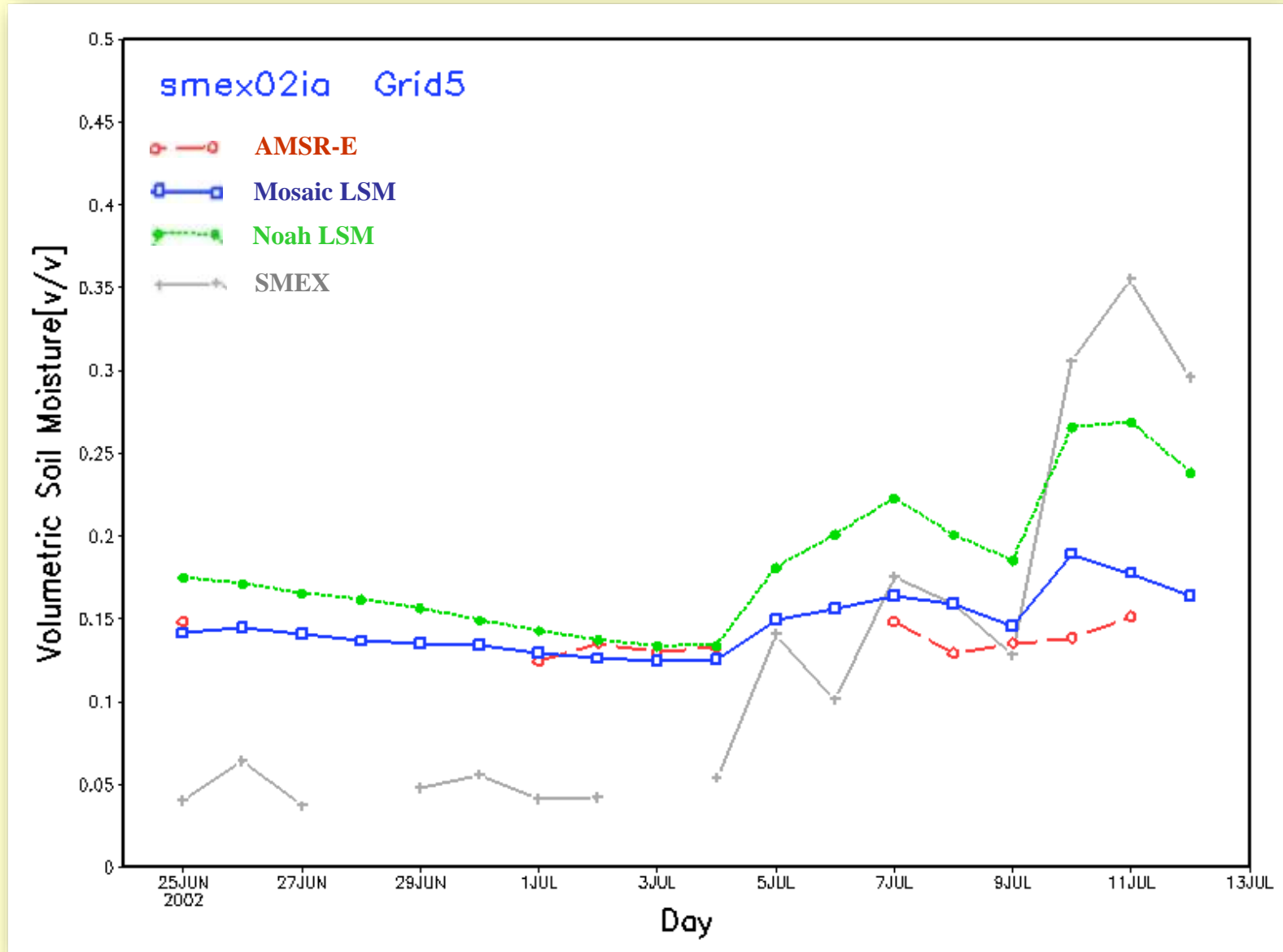
# Soil Moisture Experiments (SMEX)

<i>Name</i>	<i>Latit.</i>	<i>Long.</i>	<i>#site</i>	<i>#day</i>	<i>St Day</i>	<i>End Day</i>
<i>smex02ia</i>	<i>41.50N</i>	<i>94.00W</i>	<i>48</i>	<i>18</i>	<i>6/25</i>	<i>7/12</i>
<i>smex03ga</i>	<i>30.75N</i>	<i>84.00W</i>	<i>49</i>	<i>10</i>	<i>6/23</i>	<i>7/02</i>
<i>smex03on</i>	<i>35.75N</i>	<i>98.25W</i>	<i>36</i>	<i>16</i>	<i>7/02</i>	<i>7/17</i>
<i>smex03os</i>	<i>34.25N</i>	<i>98.50W</i>	<i>52</i>	<i>16</i>	<i>7/02</i>	<i>7/17</i>
<i>smex04az</i>	<i>31.00N</i>	<i>110.5W</i>	<i>40</i>	<i>24</i>	<i>8/03</i>	<i>8/26</i>

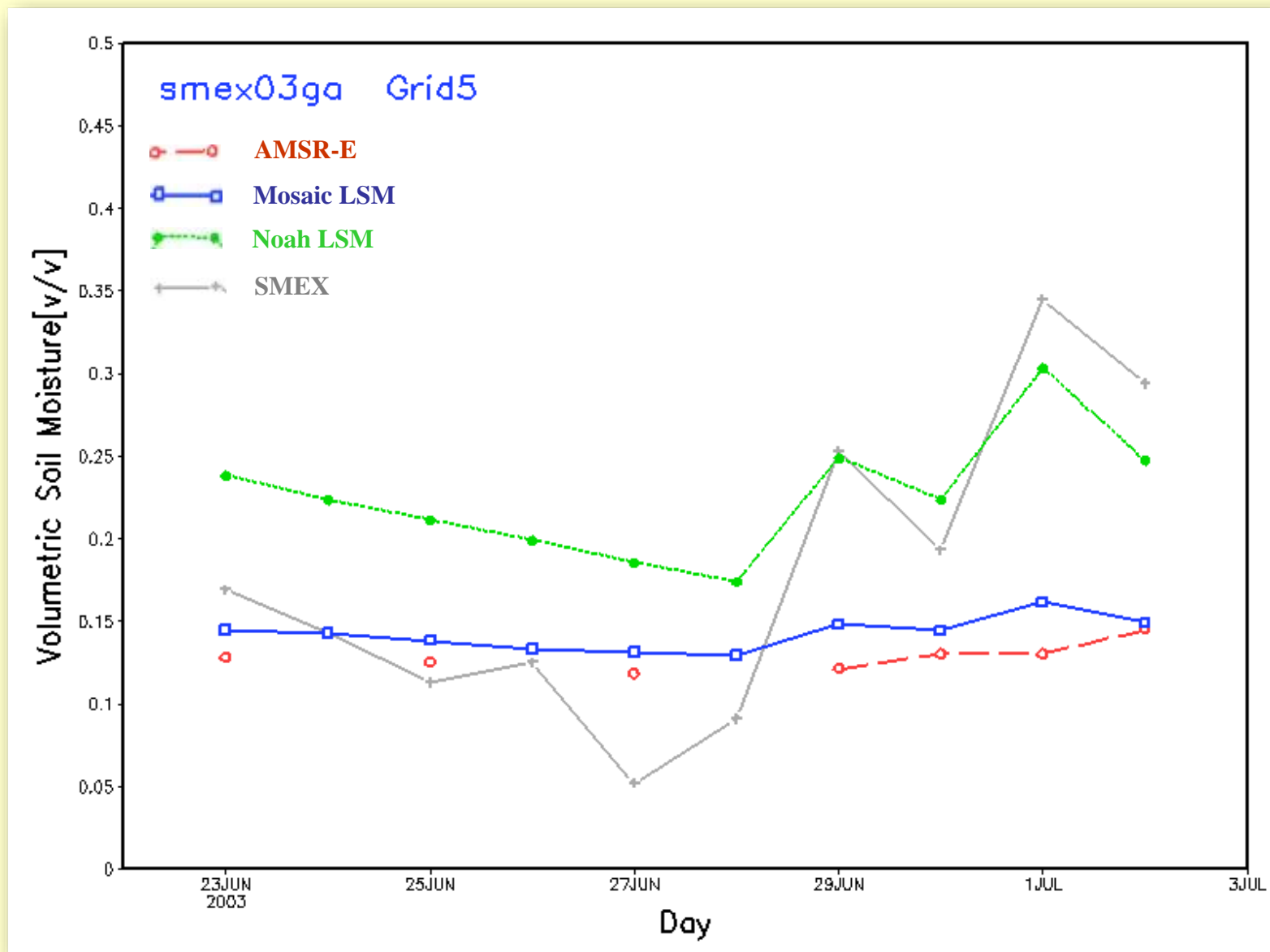
# Comparison Procedure

- ✓ *Resample AMSR-E Level2 soil moisture retrievals to 0.25 degree lat/long grids matching the LDAS 0.25 degree grids;*
- ✓ *Spin up Mosaic and Noah model simulations within NLDAS domain from 1997 to 2002;*
- ✓ *Run NLDAS-Mosaic/Noah LSMs from 2002 to 2004 to cover the time periods of AMSR-E and SMEXes data time;*
- ✓ *Average the regional sampling sites of SMEXes within each 0.25 degree lat/long grids of NLDAS simulations and AMSR-E data.*

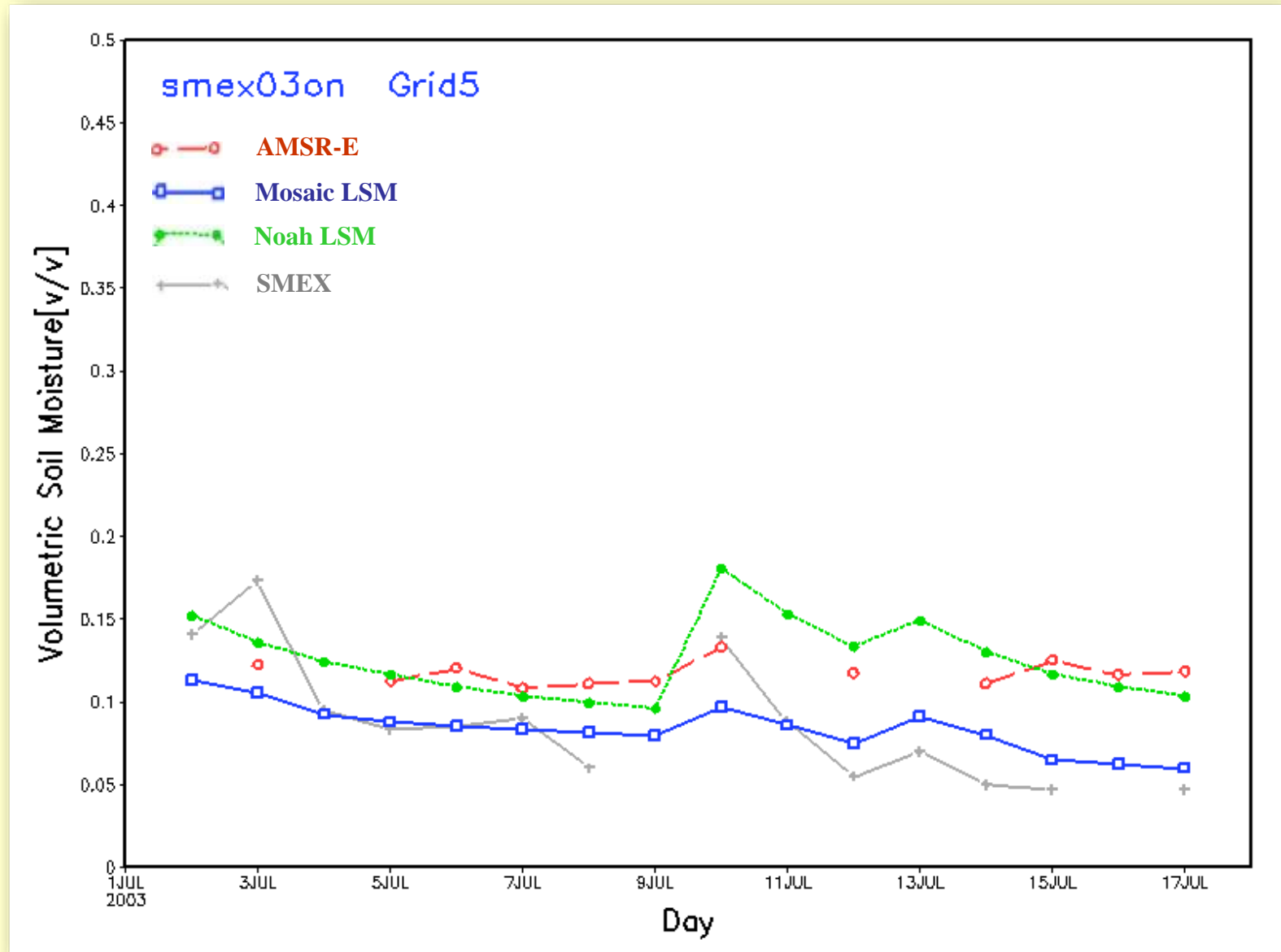
# Daily (18Z) Soil Moisture Variations



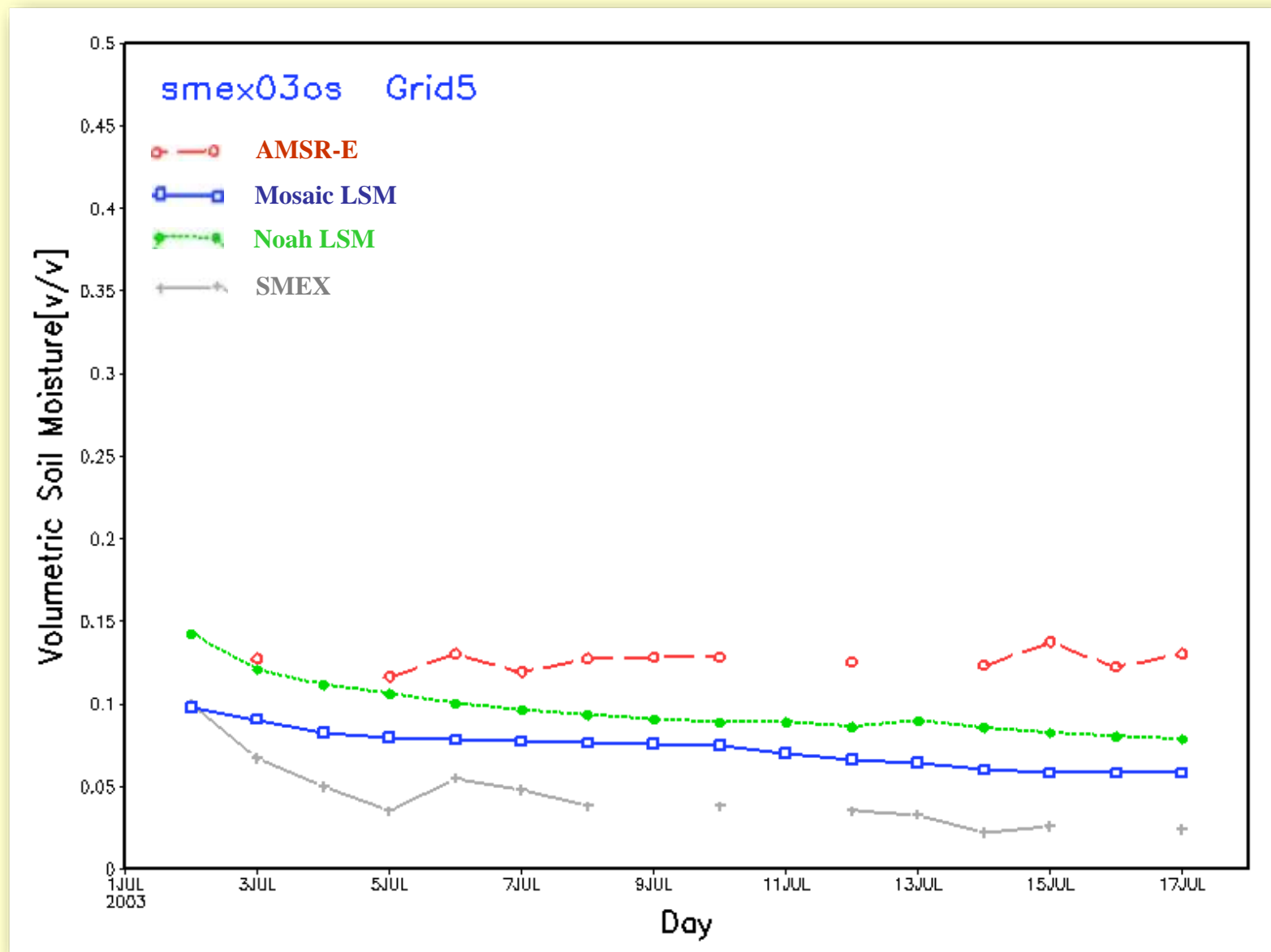
# Daily (18Z) Soil Moisture Variations



# Daily (18Z) Soil Moisture Variations

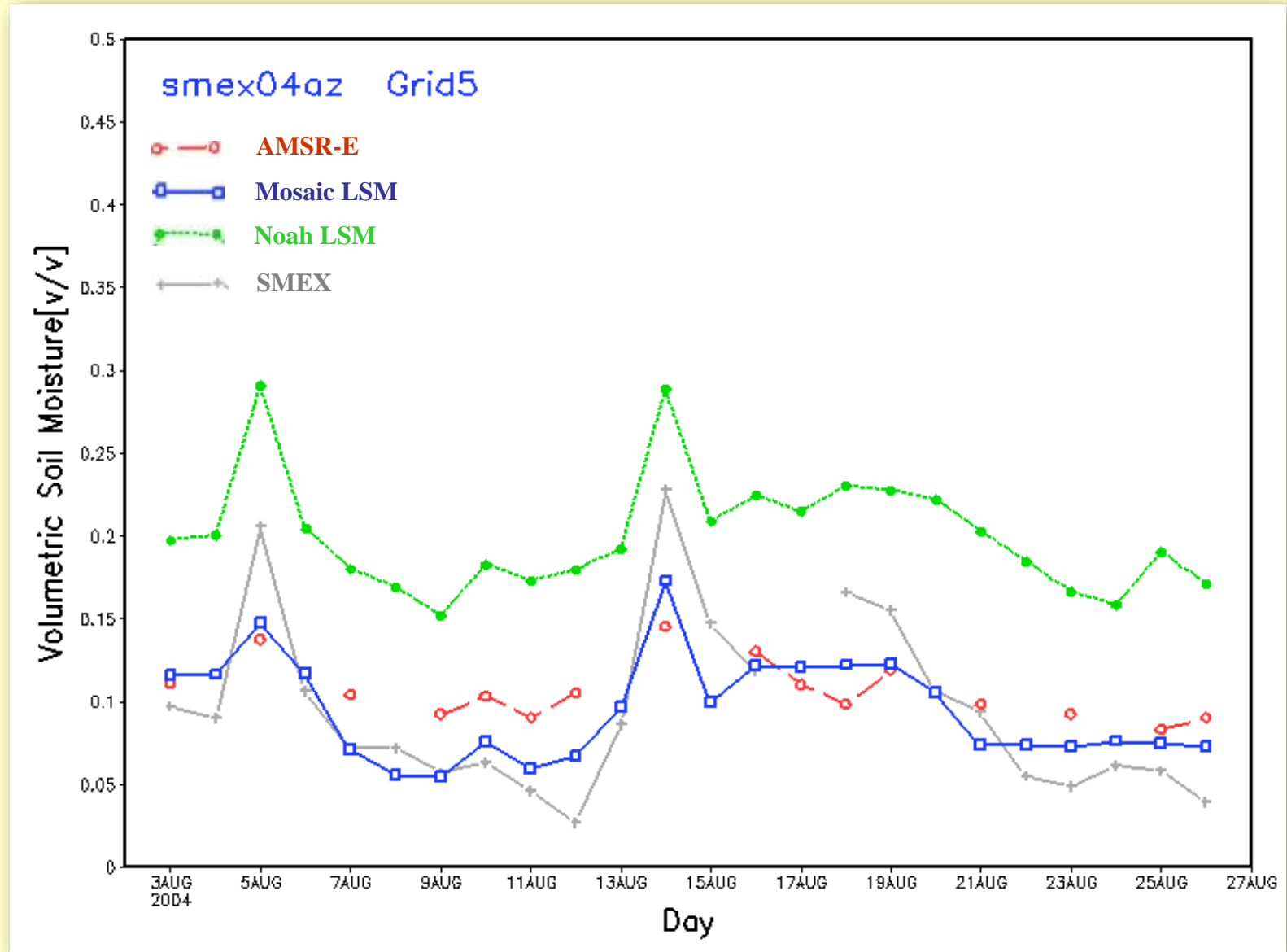


# Daily (18Z) Soil Moisture Variations

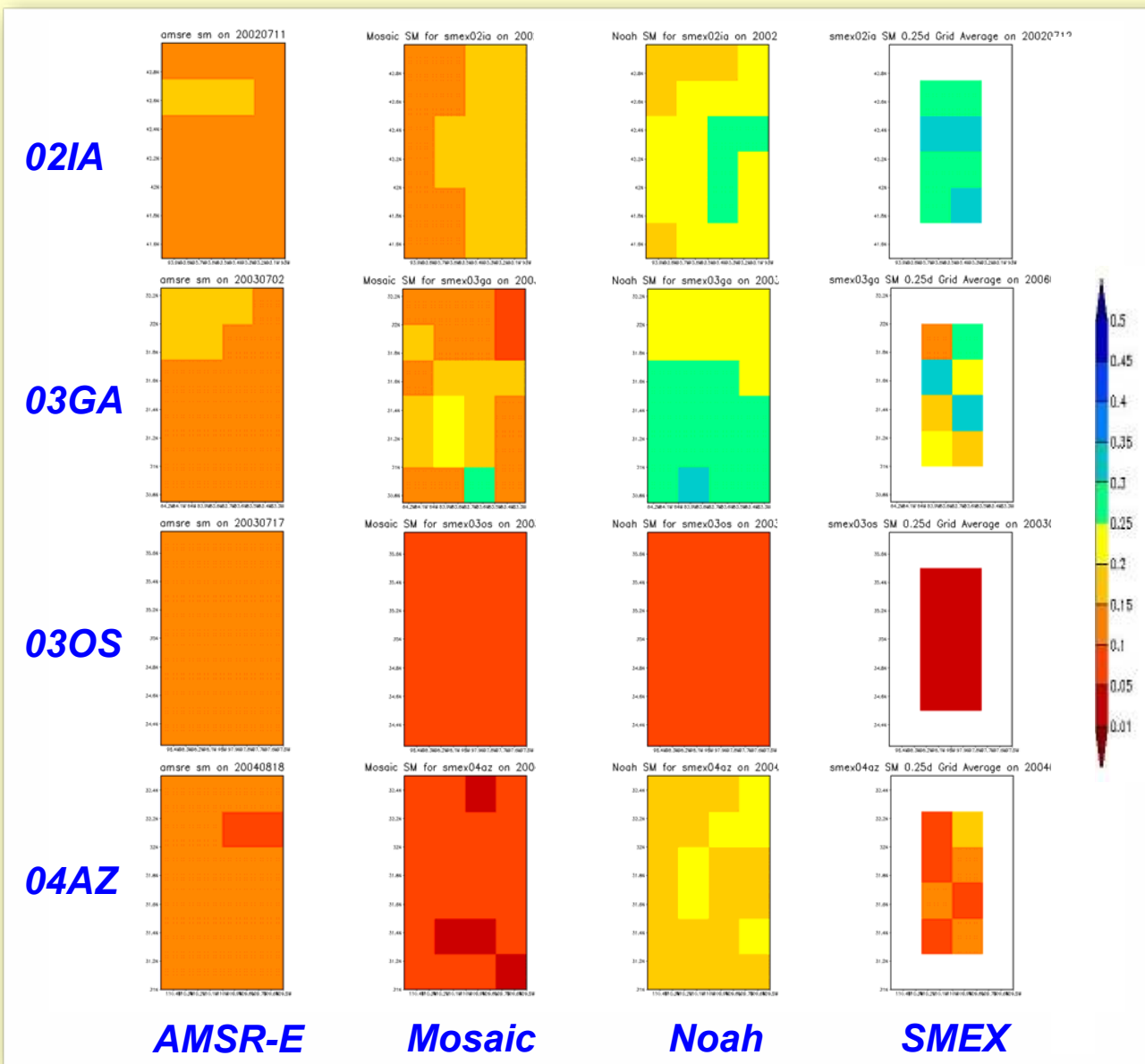




# Daily (18Z) Soil Moisture Variations



# SM Spatial Pattern Comparison

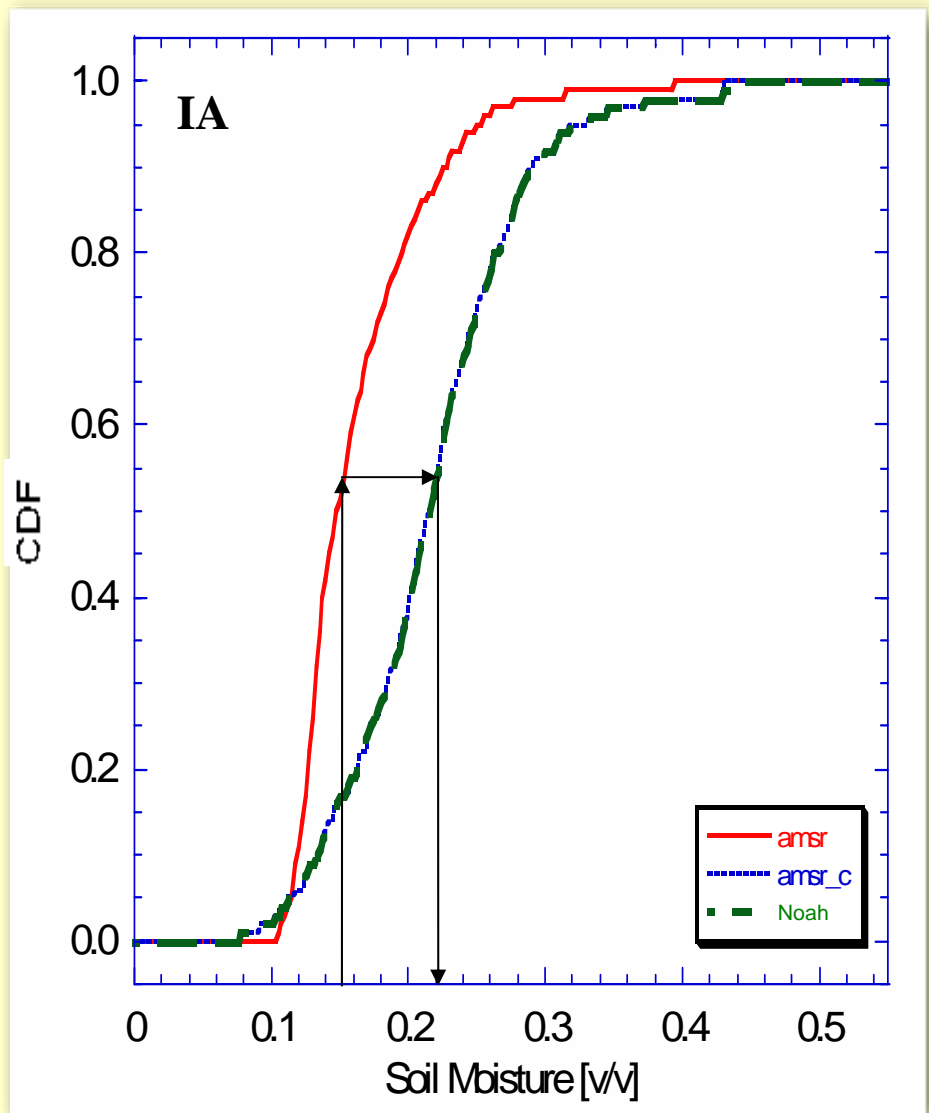
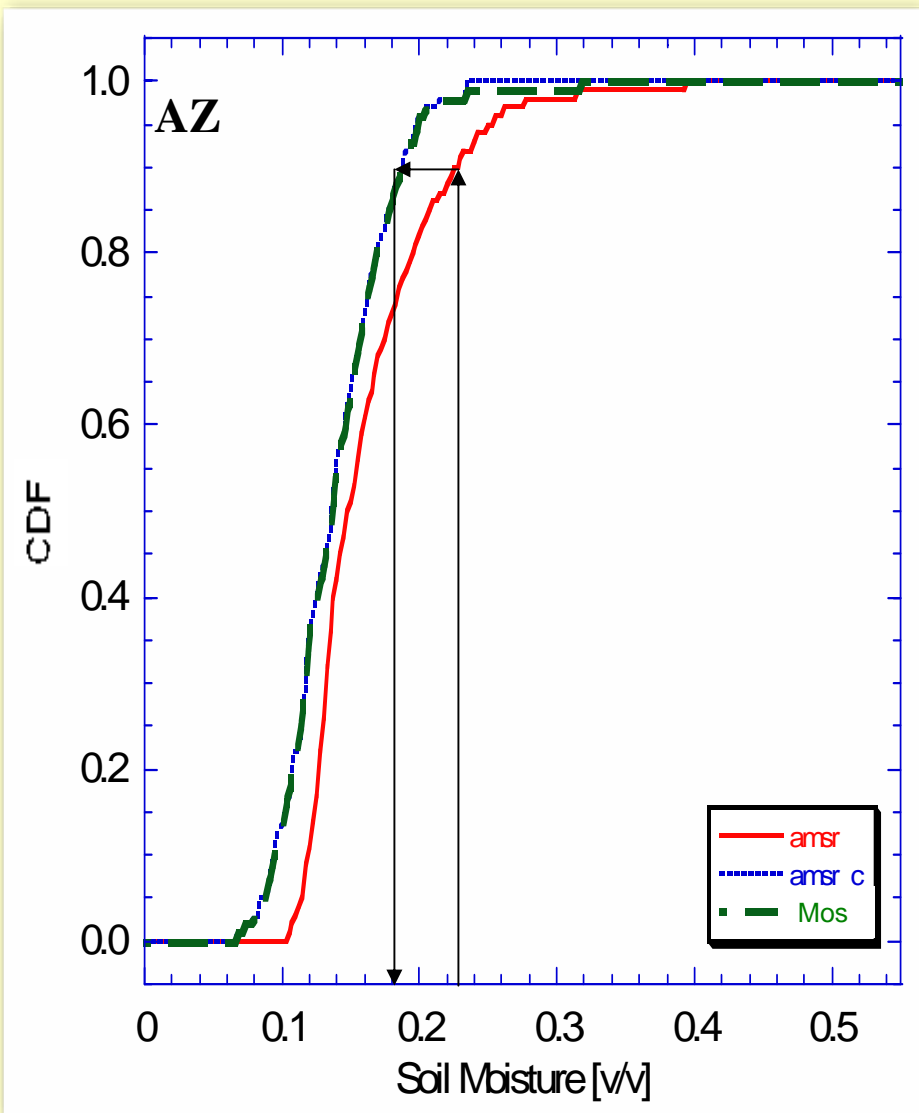


## SM Data Characteristics:

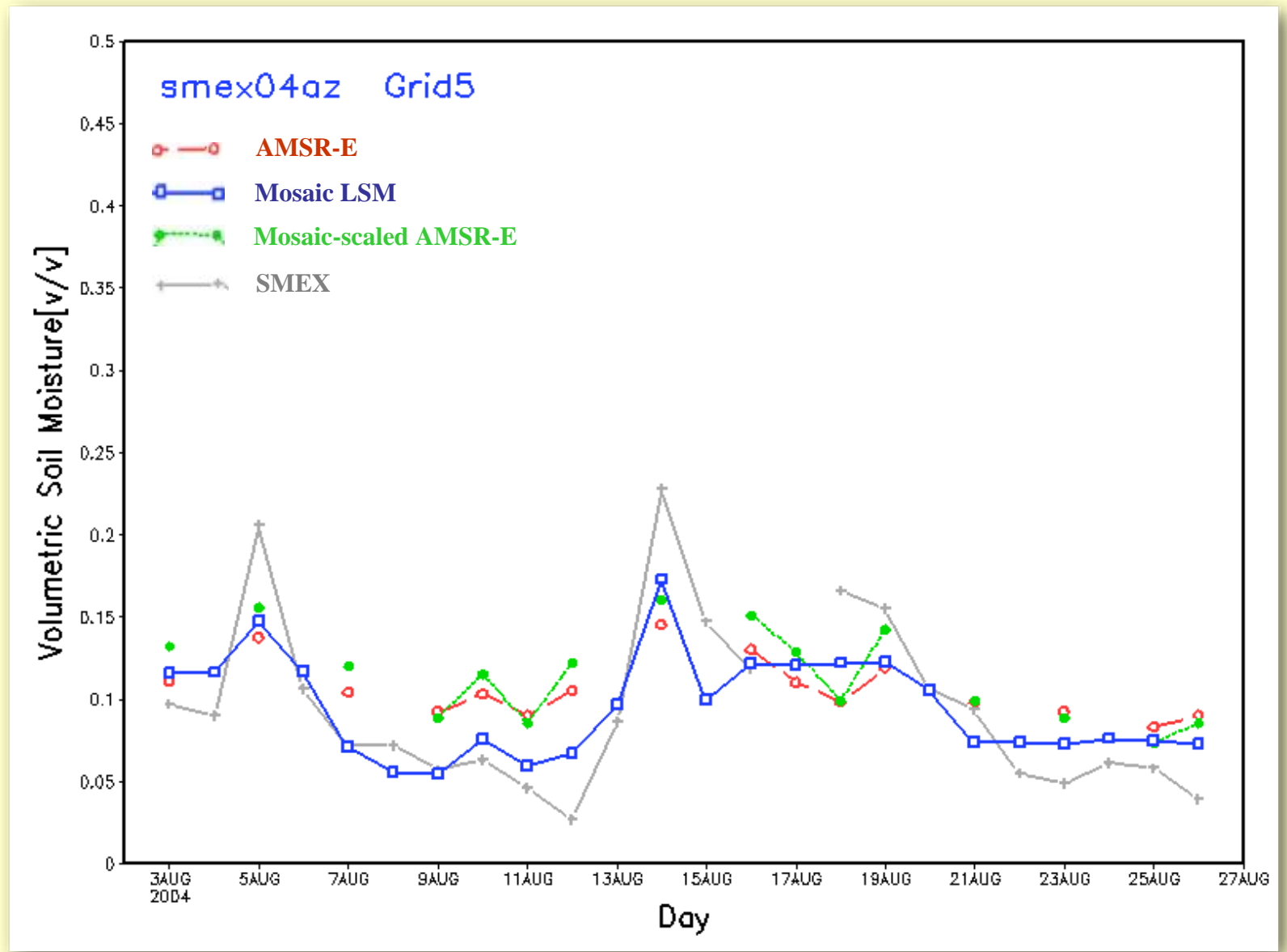
- ✓ **AMSR-E:**
  1. Global MW obs;
  2. Good time cover;
  3. Too flat?
  
- ✓ **Mosaic & Noah:**
  1. Good space cover;
  2. Too low/high?
  
- ✓ **Field Obs:**
  1. Too sparse?
  2. Too tedious?

- ✓ *Purpose: LSM simulations can have full time and space coverage, but accuracy is uncertain; AMSR-E retrievals are patchy, biased and variations damped. Data assimilation can combine them, but their scales need to be matched for DA methods such as EnKF;*
- ✓ *The cumulative distribution function matching method used in Reichle & Koster (2004) can scale the AMSR-E retrievals to the simulations of LSMs to be used for assimilation;*
- ✓ *How will the scaled AMSR-E data be compared with the model simulations?*

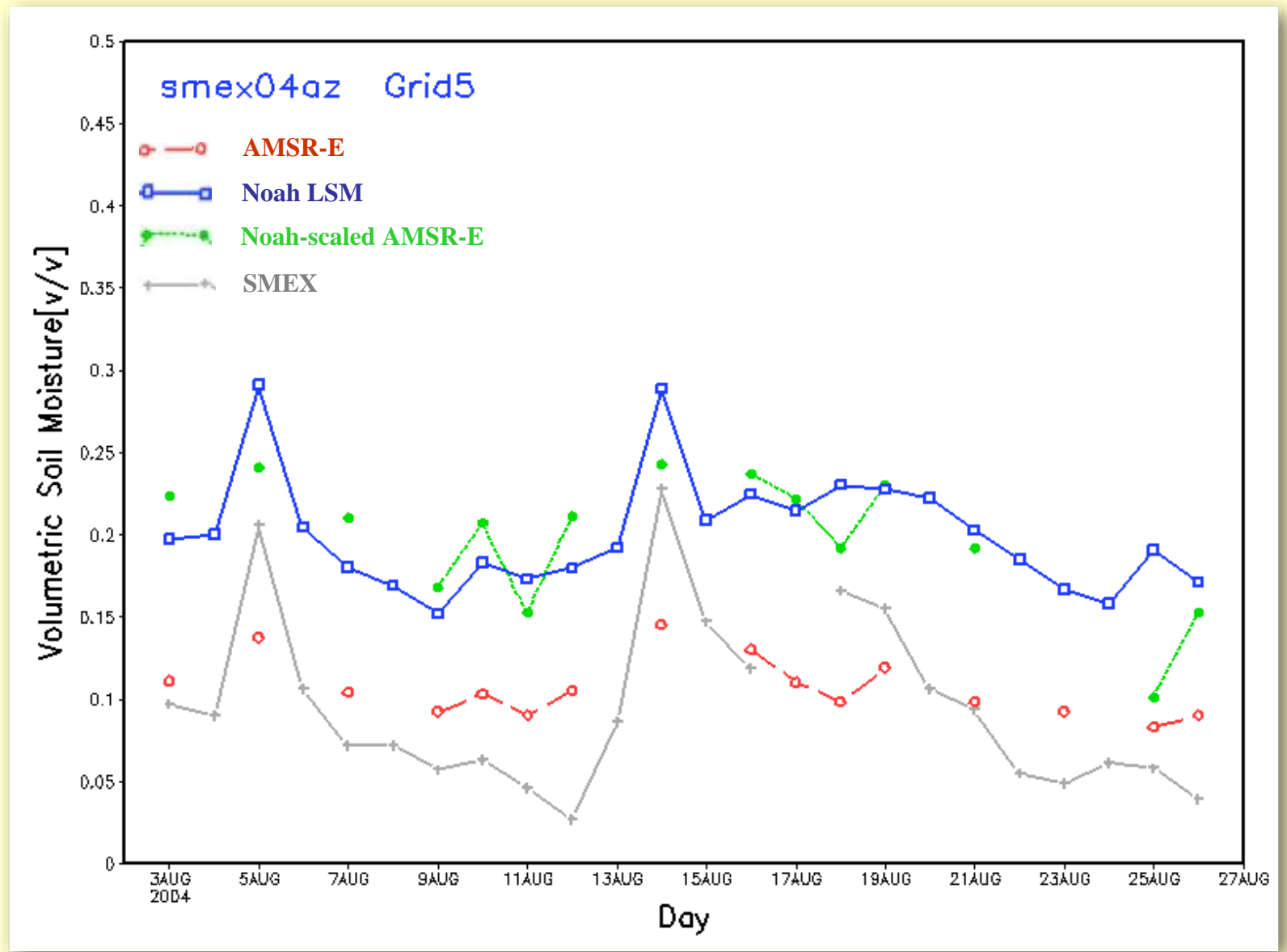
# CDFs for SMEX Sites



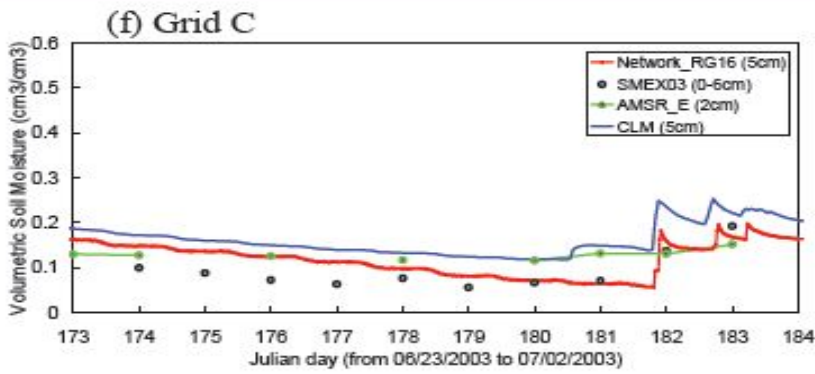
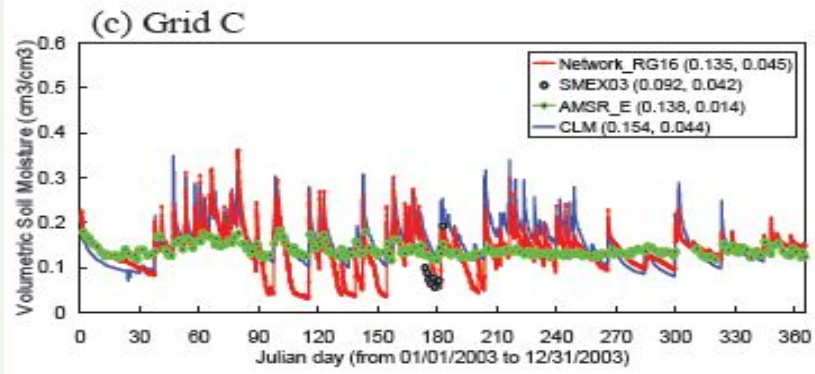
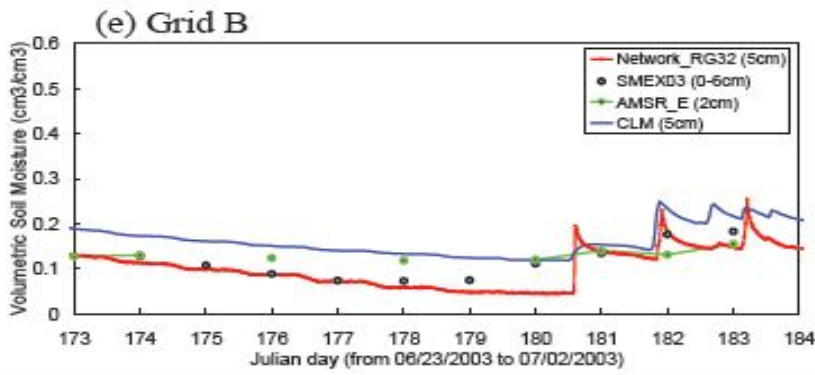
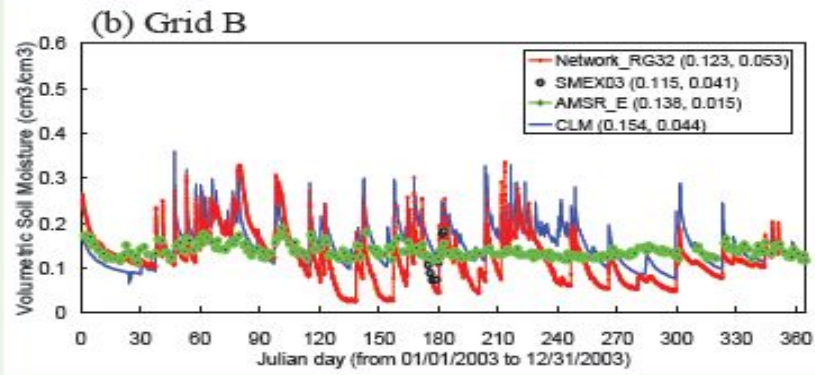
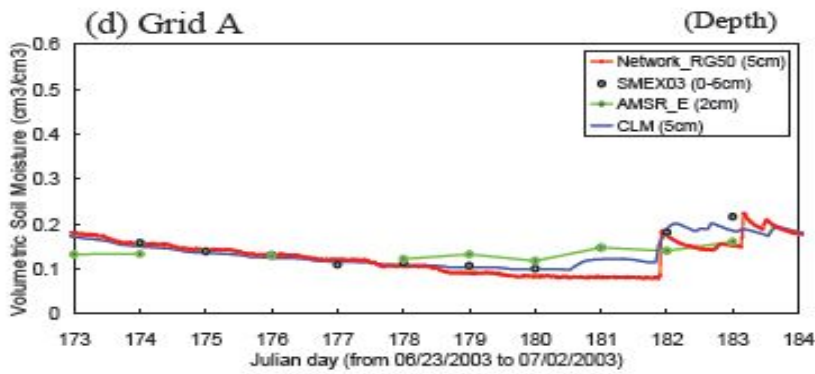
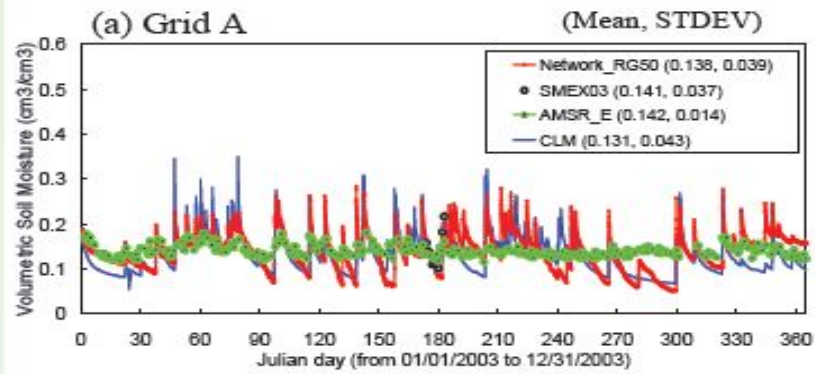
# Scaled AMSR-E SM vs Model Simulations



# Scaled AMSR-E SM vs Model Simulations

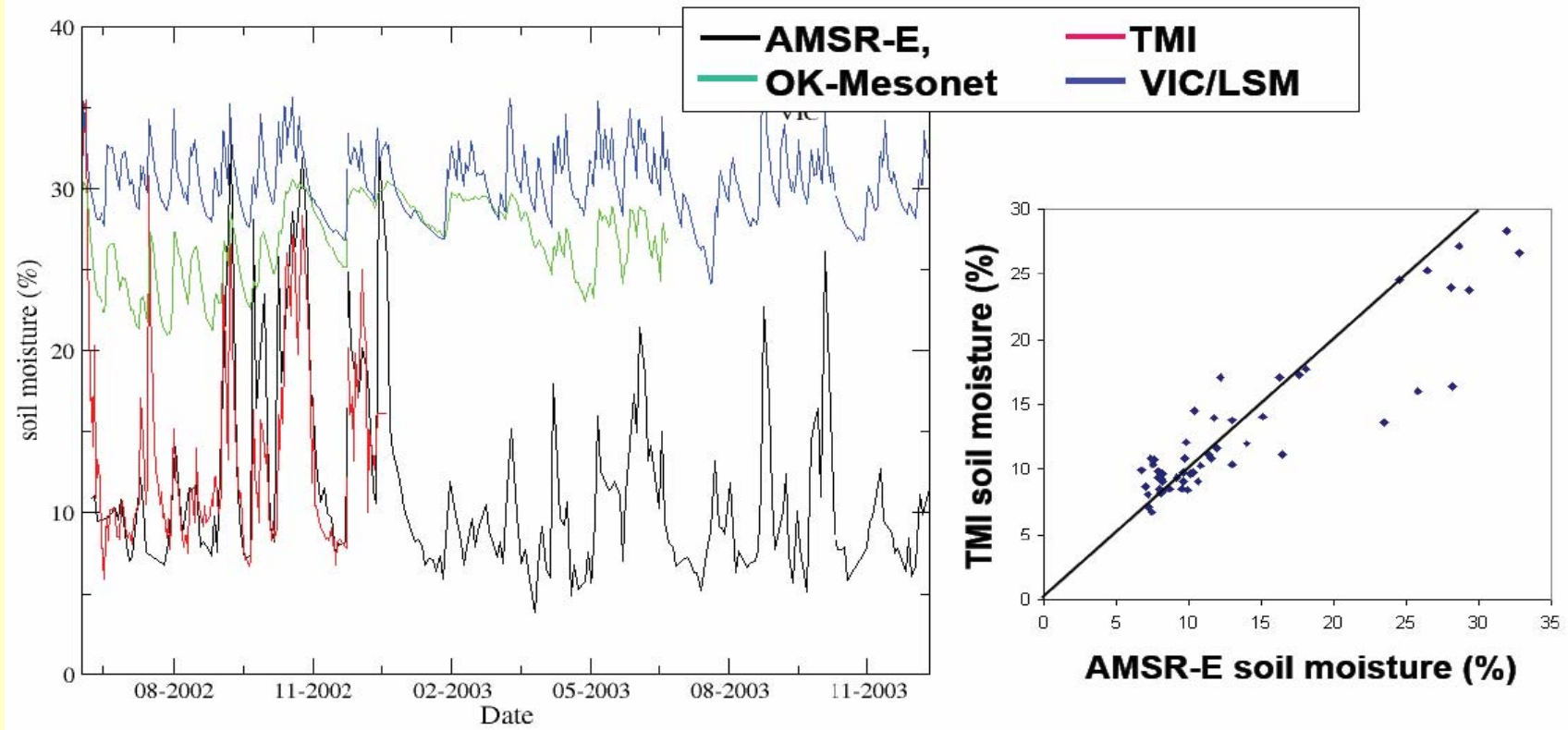


# UNH's Comparison Results (Choi & Jacobs, 2006)



# PU's Comparison Results (McCabe et al, 2004)

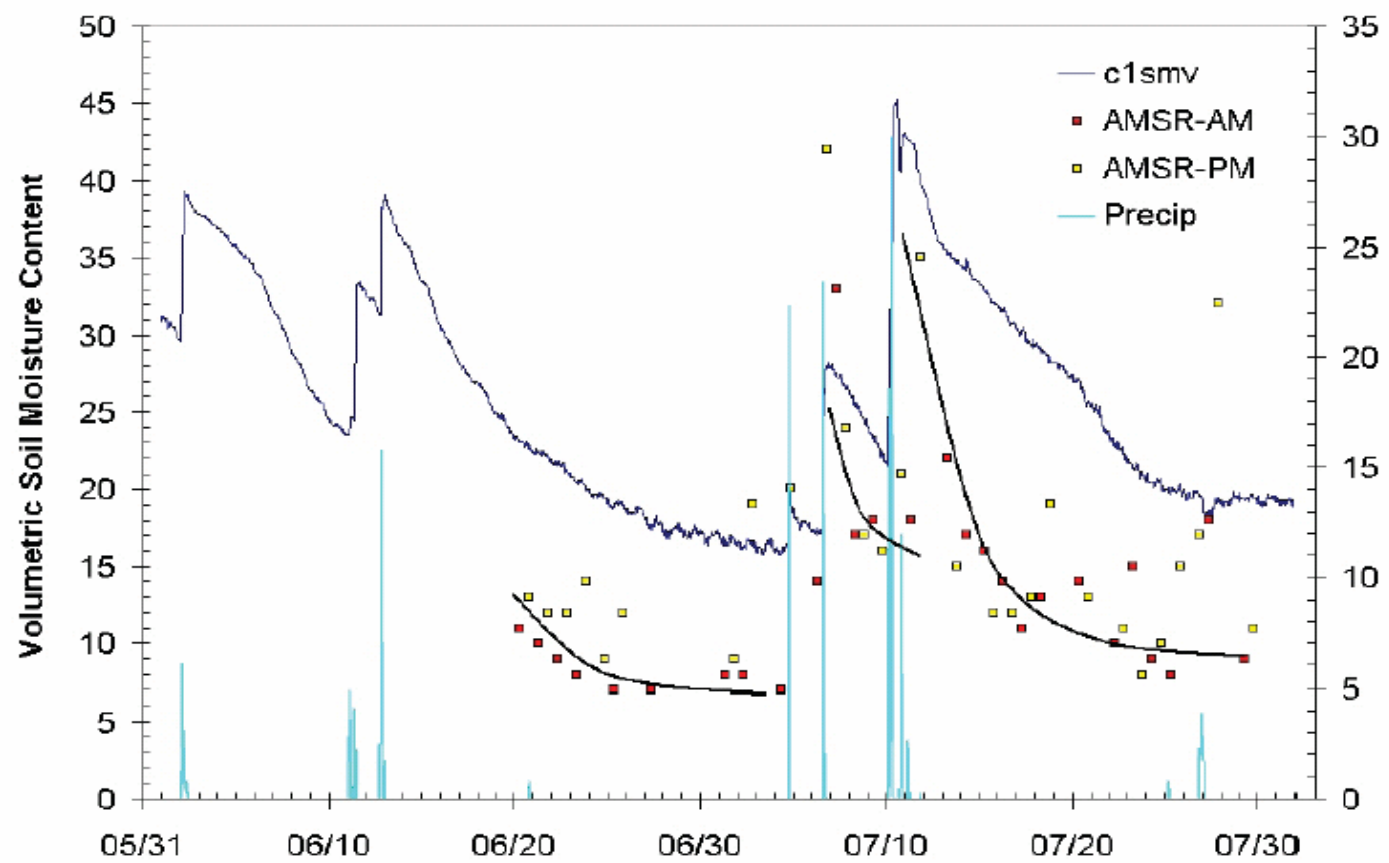
## PU/AMSR-E X-Band Soil Moisture Comparisons with PU/TMI X-Band Soil Moisture



Lesson: Retrievals consistent across sensors, but different from *in-situ*



## SMEX02: PU/AMSR-E X-Band Soil Moisture Comparison with the ARS SCAN Soil Moisture Monitoring Site





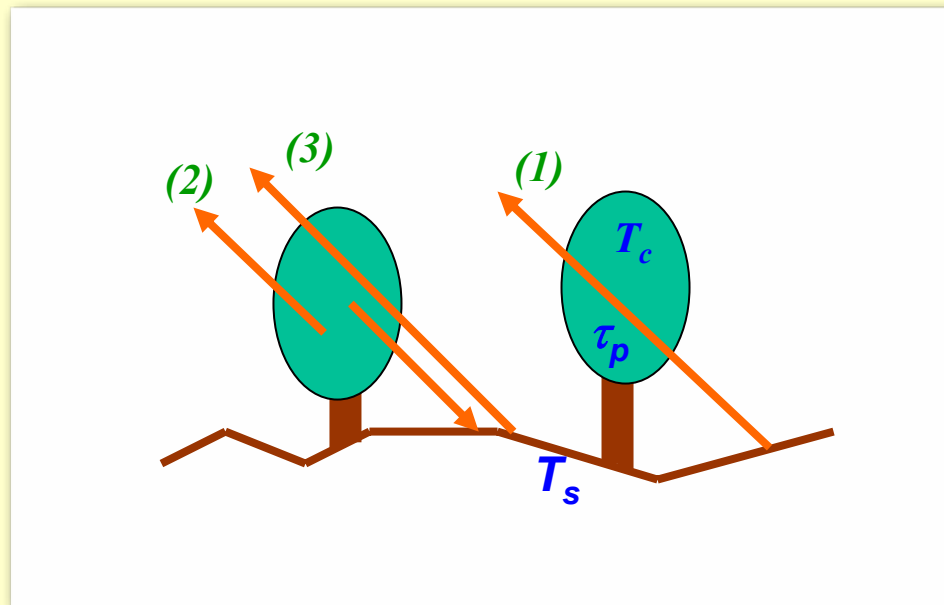
- ✓ ***AMSR-E soil moisture retrievals, Mosaic and Noah LSM simulations are compared with SMEXes field measurements at the 0.25 degree grid scale;***
- ✓ ***AMSR-E soil moisture retrievals mostly followed the soil moisture dynamic trends of either model simulations or field measurements;***
- ✓ ***But AMSR-E soil moisture retrievals are generally too wet for dry surfaces and too dry for wet surfaces;***
- ✓ ***The anticipated utilization of AMSR-E soil moisture retrievals is to assimilate them into a LSM after matching their CDFs;***
- ✓ ***Further work is needed to improve the AMSR-E retrievals.***

- ❖ *Evaluation of NASA's Current AMSR-E Soil Moisture Data Product*
- ❖ **An Alternative AMSR-E Soil Moisture Data Product from NOAA-USDA**
- ❖ *Retrieving High Resolution Soil Moisture From Hydros*

$$T_{Bp} = T_s e_{r,p} \exp(-\tau_p/\cos\theta) + \quad (1)$$

$$T_c (1 - \omega_p) [1 - \exp(-\tau_p/\cos\theta)] + \quad (2)$$

$$T_c (1 - \omega_p) [1 - \exp(-\tau_p/\cos\theta)] R_{r,p} \exp(-\tau_p/\cos\theta) \quad (3)$$



## NASA's AMSR-E SM Baseline Retrieval Algorithm:

$$\min\{ \chi^2 = \sum_{i=1}^6 \left( \frac{T_{B,i}^{obs} - T_{B,i}^{cmp}}{\sigma_i} \right)^2 \}$$

$$T_{B,i}^{cmp} = T_{skin} \{ e_{r,p} \exp(-\tau_i / \cos\theta) + (1 - \omega) [1 - \exp(-\tau_i / \cos\theta)] [1 + R_{r,i} \exp(-\tau_i / \cos\theta)] \}$$

$$\tau_i = b * VWC$$

$$R_{r,i} = R_s \exp(h \cos^2\theta)$$

$$R_s = f(\epsilon) \quad \text{-- Fresnel Equation}$$

$$\epsilon = g(SM) \quad \text{-- Mixing model}$$

$$T_{B,i}^{obs} = T_{B06h}, T_{B06v}, T_{B10h}, T_{B10v}, T_{B18h}, T_{B18v}$$

## An Alternative AMSR-E SM Retrieval Algorithm – Single Channel Retrieval (SCR):

$$T_{B10h} = T_s [1 - R_r \exp(-2\tau / \cos\theta)]$$

$$R_r = R_s \exp(h \cos^2\theta)$$

$$R_s = f(\epsilon) \quad \text{-- Fresnel Equation}$$

$$\epsilon = g(\text{SM}) \quad \text{-- Mixing model}$$

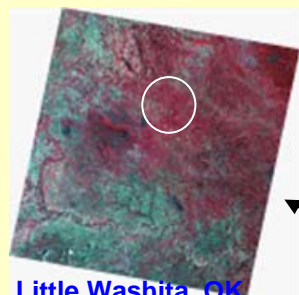
$$T_s = \text{reg}_1(T_{B37v}) \text{ or } T_s^{\text{LSM}}$$

$$\tau = b * \text{VWC}$$

$$\text{VWC} = \text{reg}_2(\text{NDVI})$$

# Experimental Alternative AMSR-E SM Product (1)

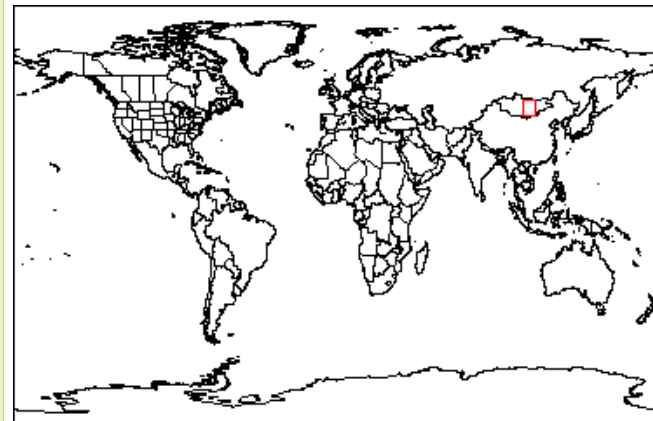
- ✓ The **SCR algorithm** is adopted to take advantage of optical **VWC observations**.
- ✓ Use only **AMSR-E TB10h** as primary input and **AMSR-E TB37v** and **MODIS/AVHRR NDVI** as ancillary input.
- ✓ To be Tested against **field data** from two sites of **USDA's ground observation network** and one site in **Mongolia** for the year 2003.



AMSR-E U.S. Soil Moisture Validation Sites

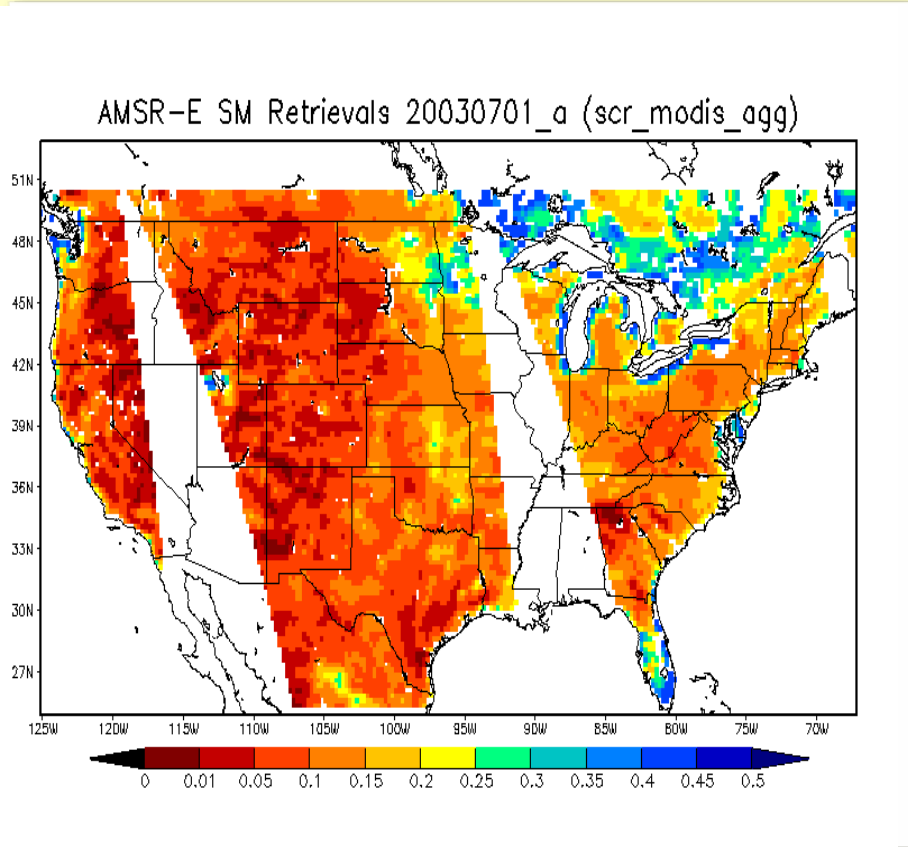
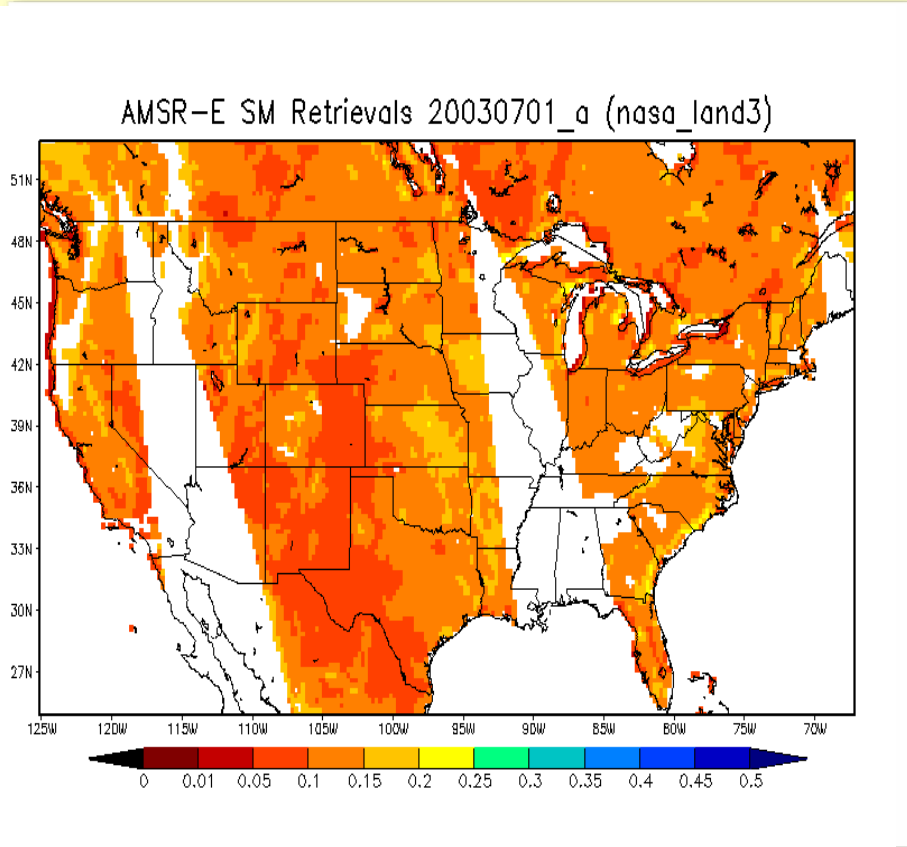


Mongolian Soil Moisture Validation Site



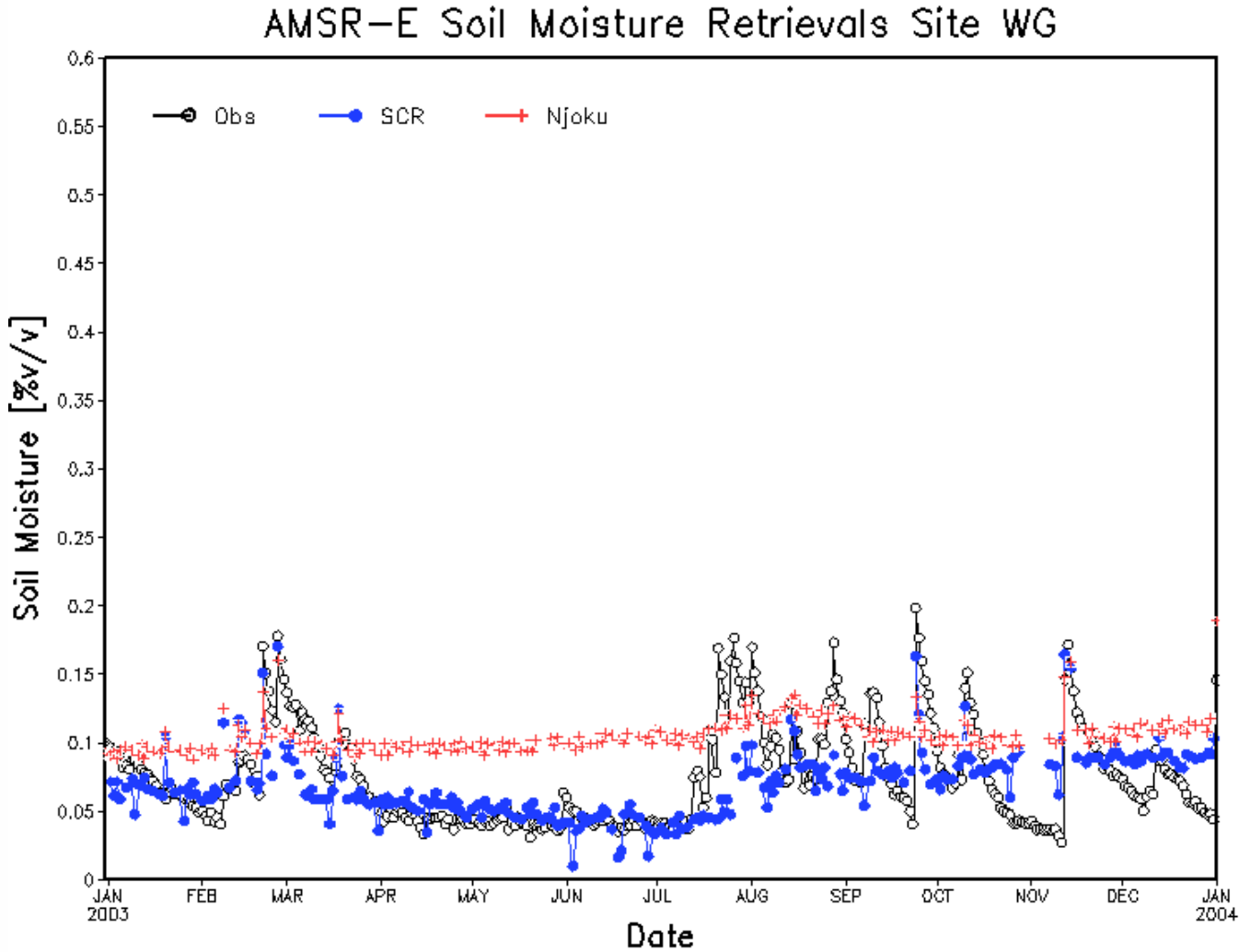


## Spatial Map

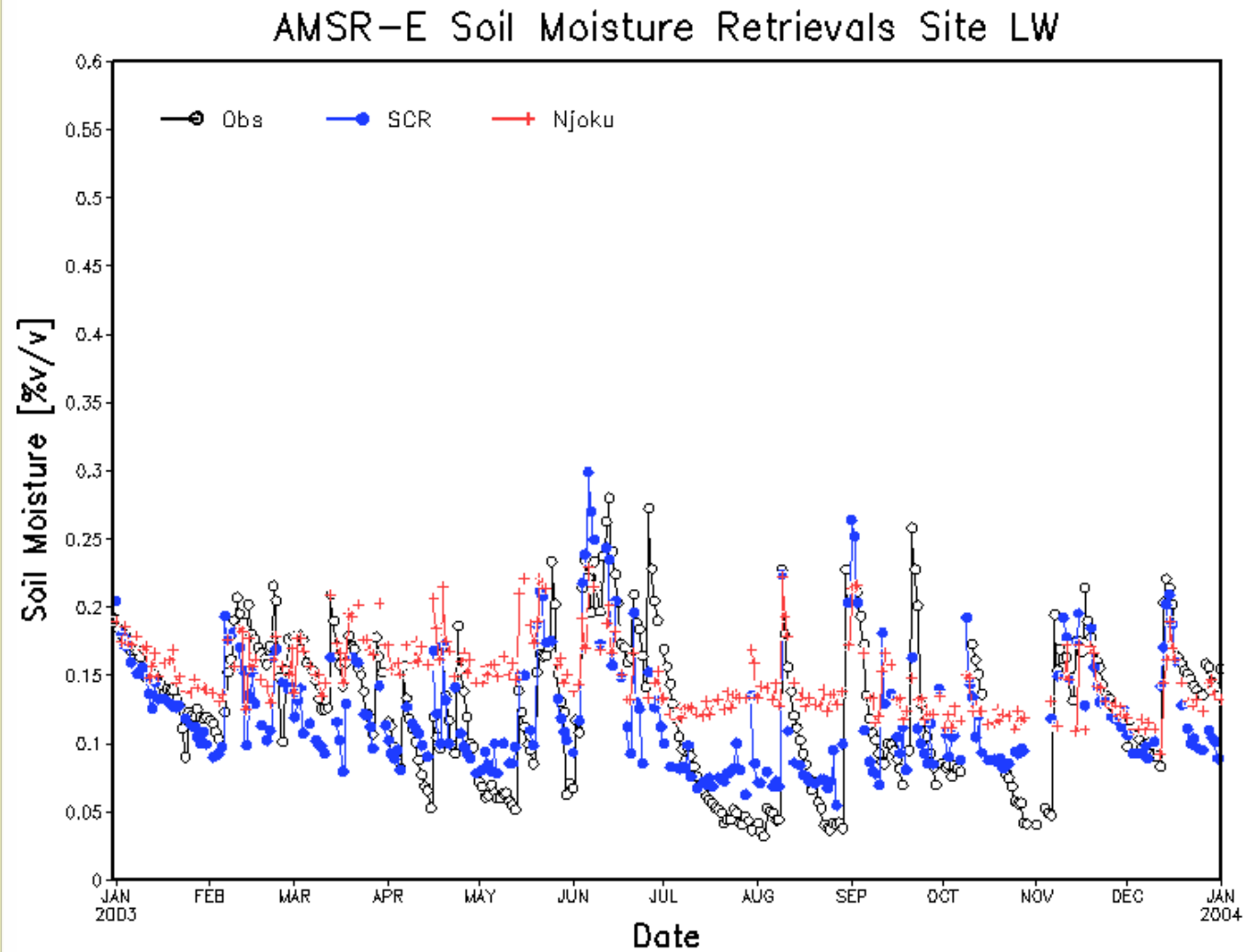


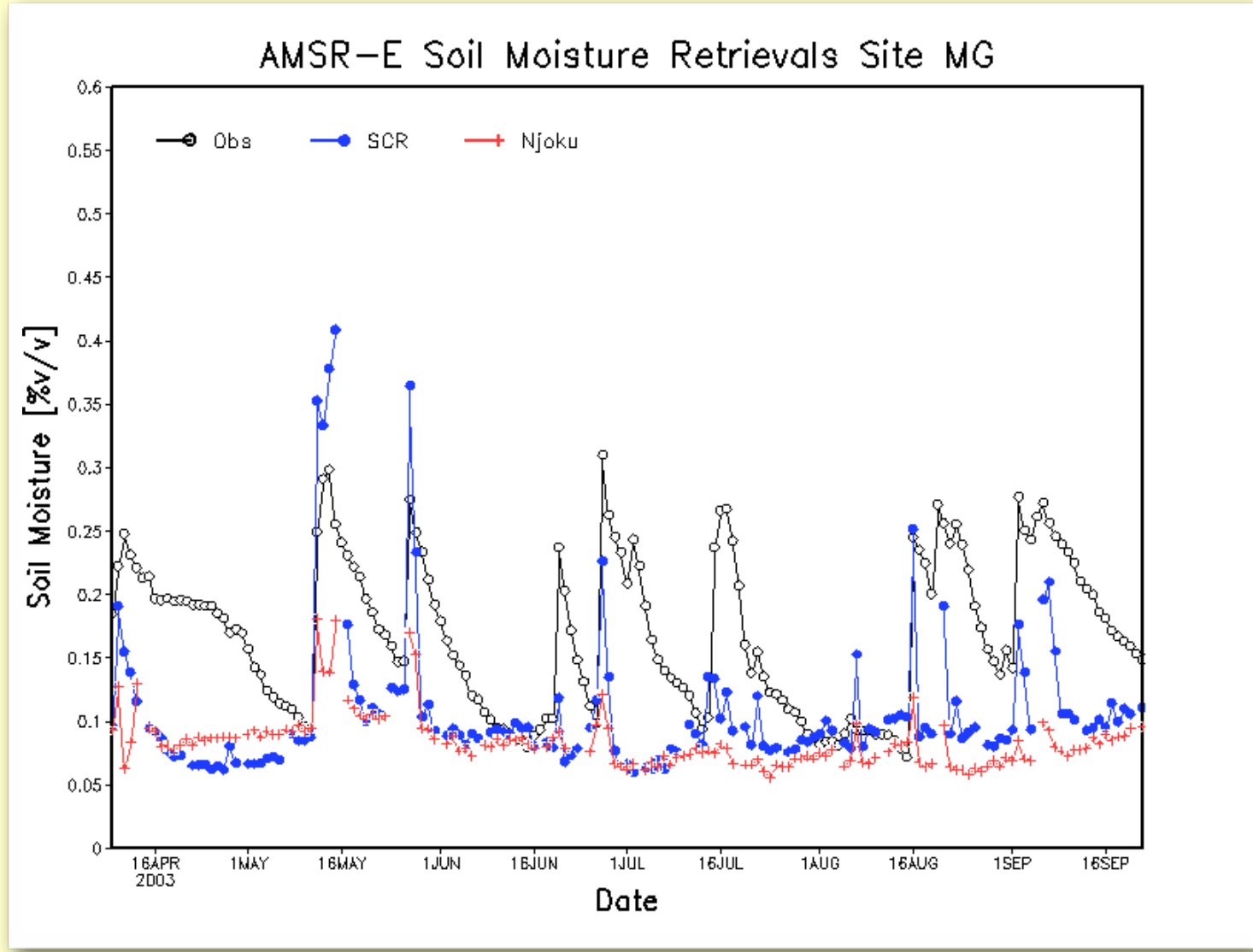


# Experimental Alternative AMSR-E SM Product (3)



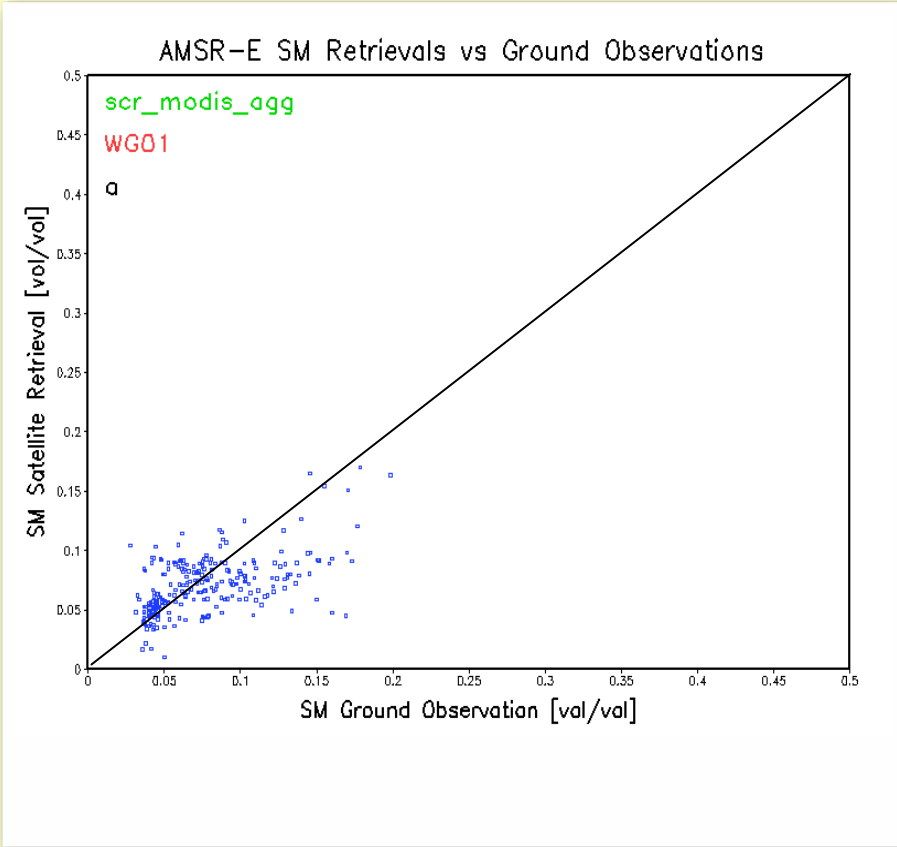
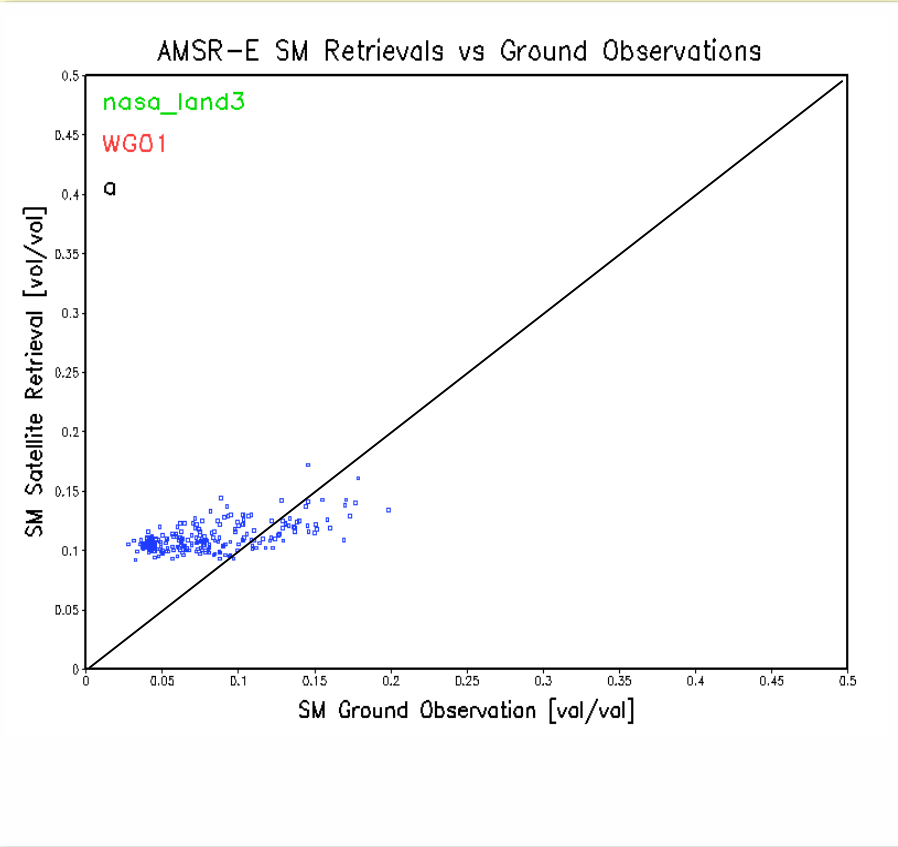
# Experimental Alternative AMSR-E SM Product (4)





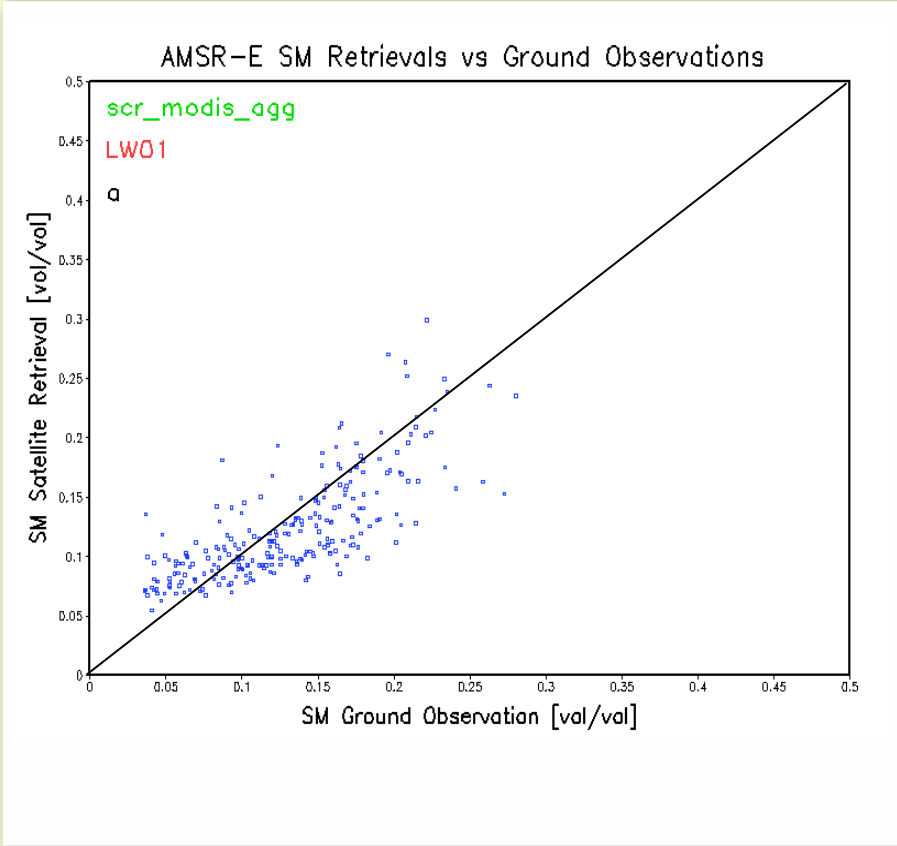
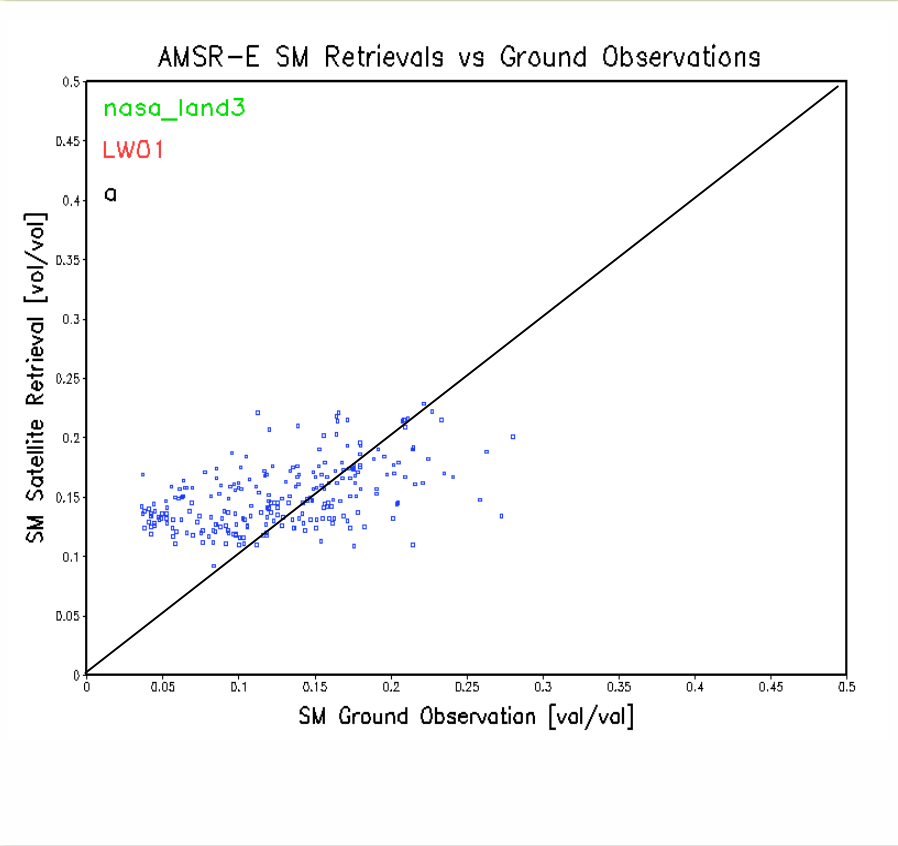


## Scatter Plot



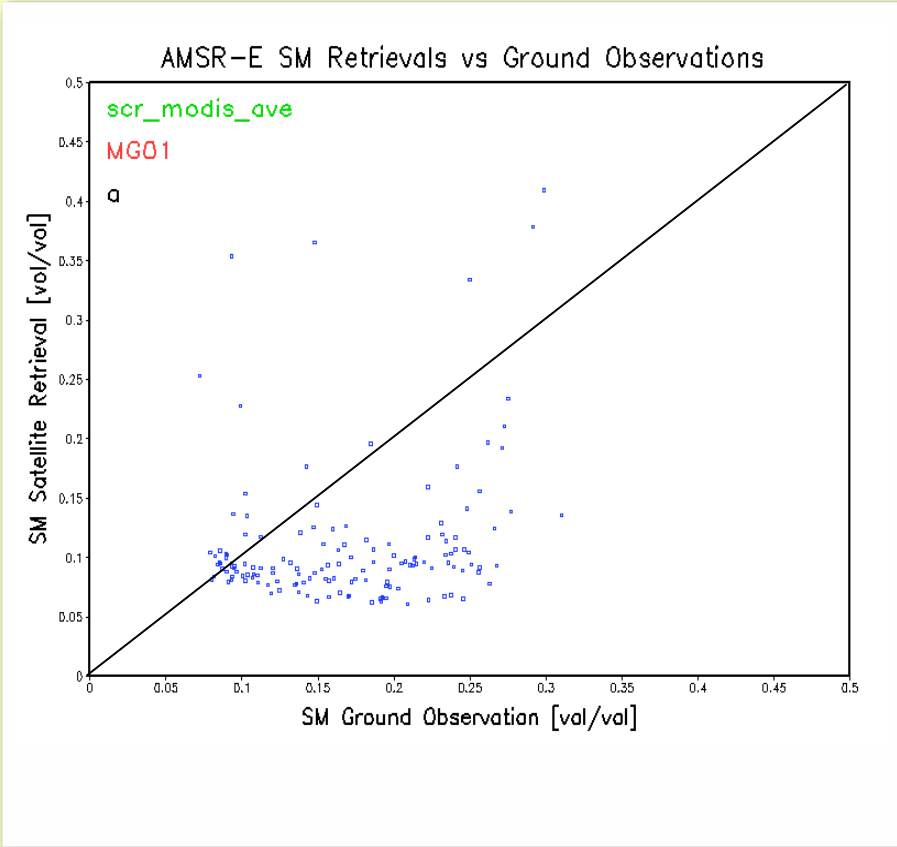
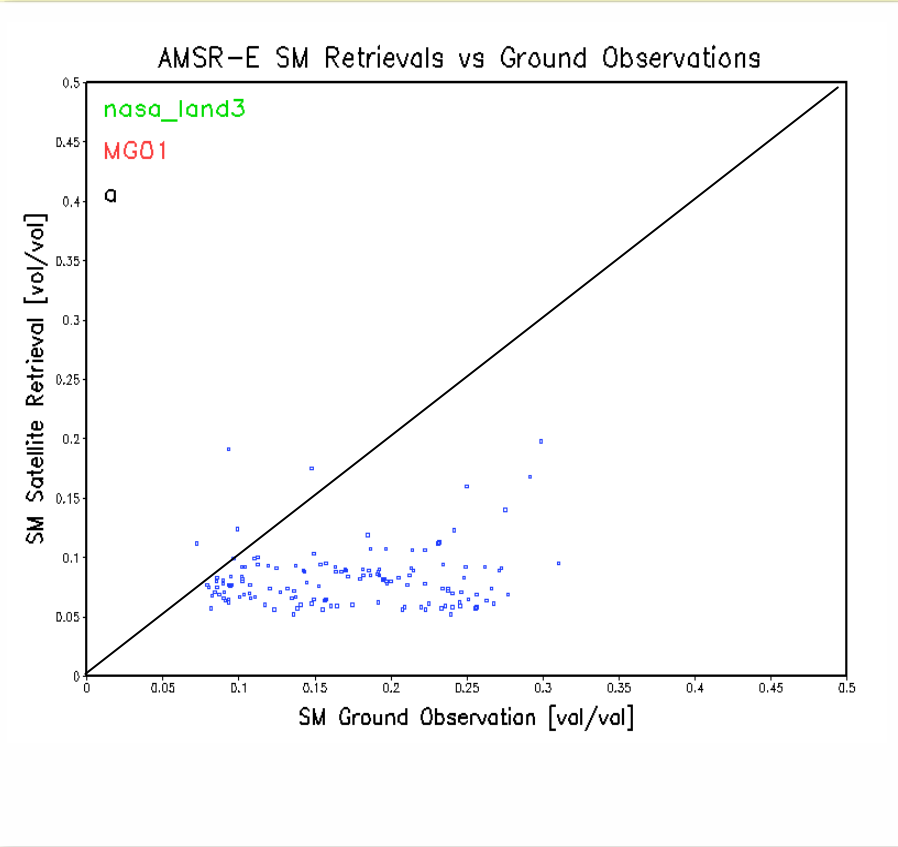


## Scatter Plot





## Scatter Plot



## Error Statistics

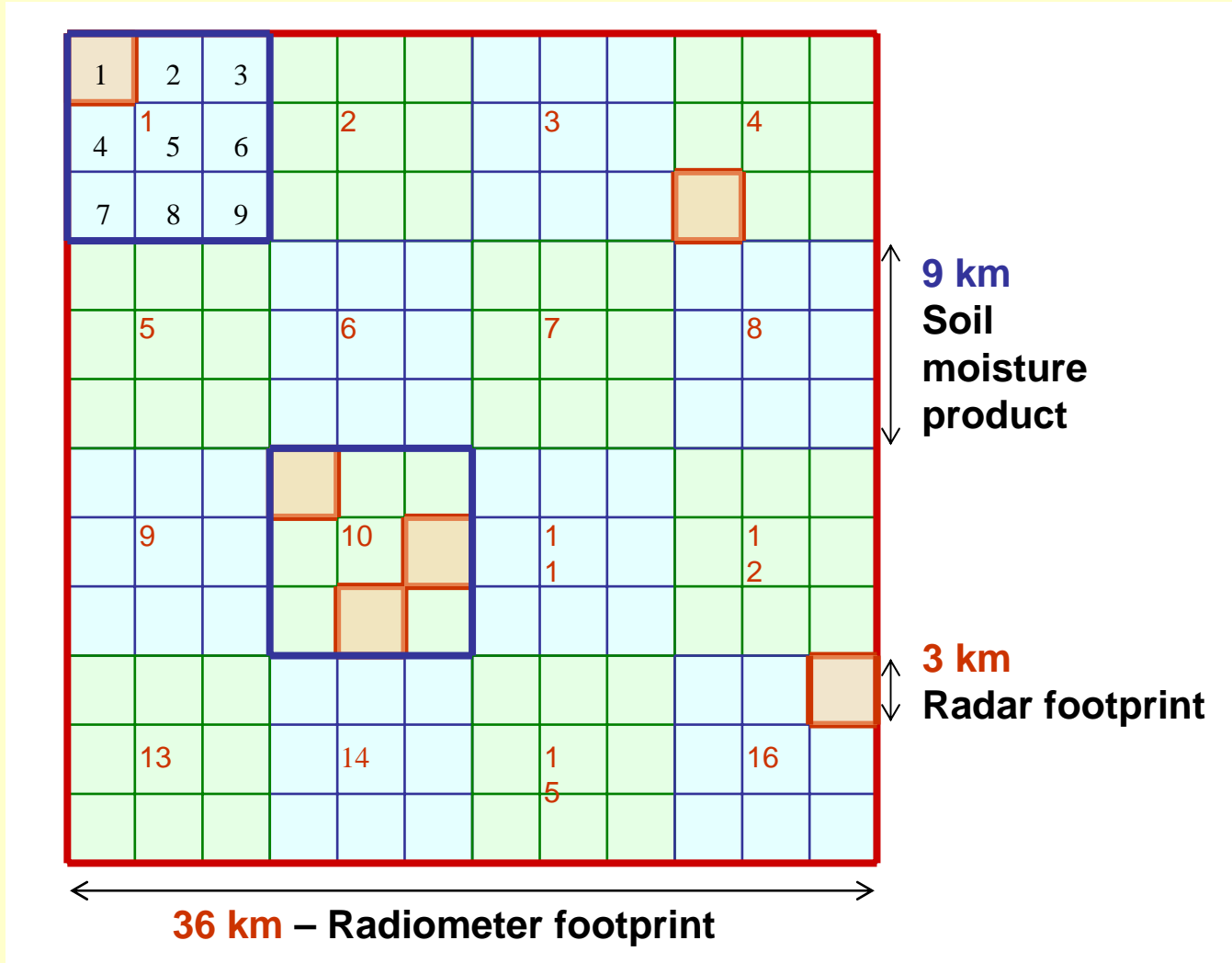
<b>Site</b>	<b>Alg</b>	<b>RMSE</b>	<b>Bias</b>	<b>R</b>	<b>Slope</b>
<b>WG01</b>	<b>NASA</b>	1.4%	0.4%	0.955	1.22
	<b>SCR</b>	1.0%	0.0%	0.947	0.91
<b>LW01</b>	<b>NASA</b>	1.4%	0.3%	0.960	1.04
	<b>SCR</b>	1.6%	0.1%	0.970	0.94
<b>MG01</b>	<b>NASA</b>	2.5%	1.1%	0.786	1.53
	<b>SCR</b>	2.4%	0.3%	0.775	0.81

- ❖ *Evaluation of NASA's Current AMSR-E Soil Moisture Data Product*
- ❖ *An Alternative AMSR-E Soil Moisture Data Product from NOAA-USDA*
- ❖ **Retrieving High Resolution Soil Moisture From Hydros**

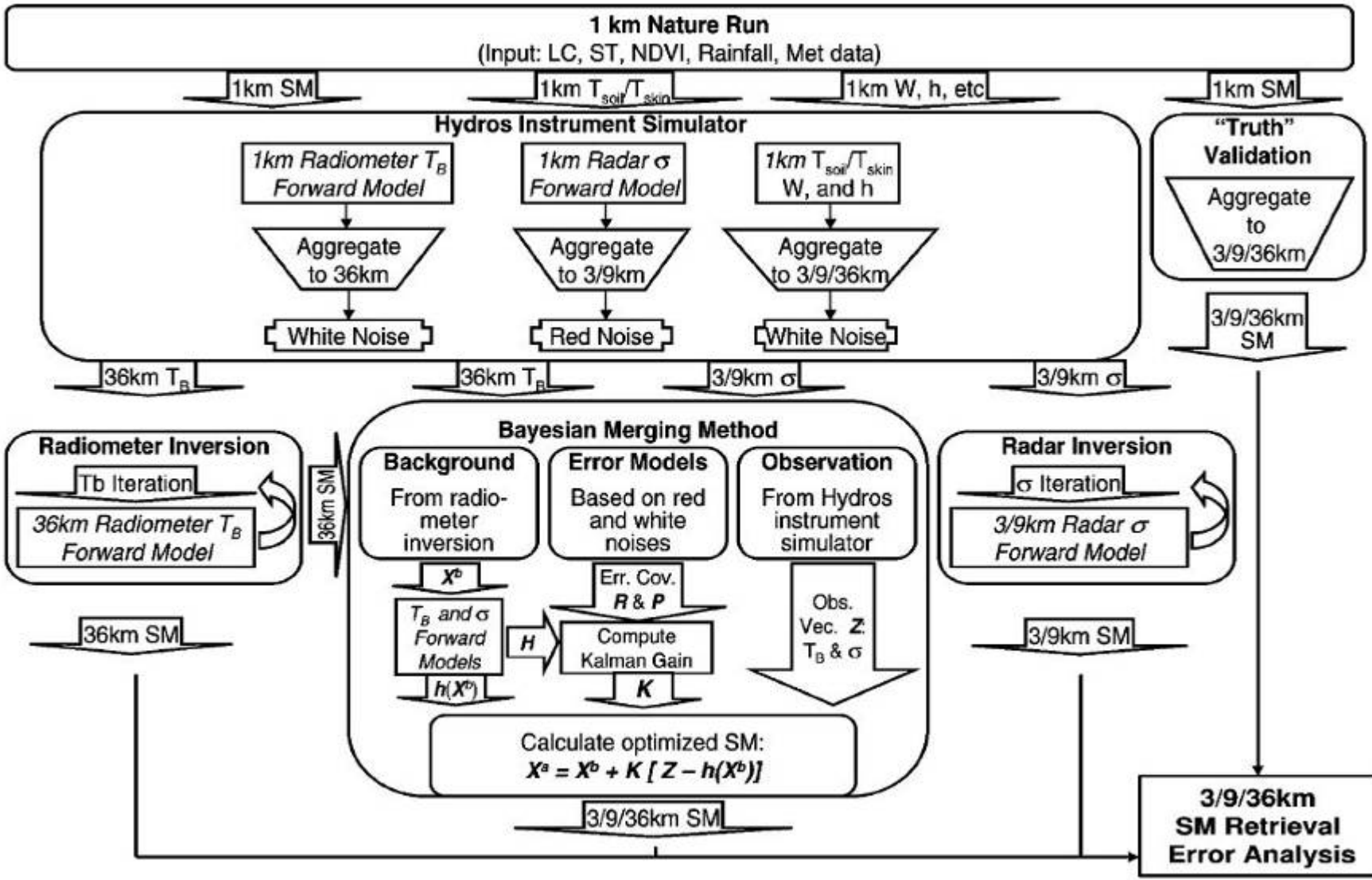




## Hydros Sensor Model in the OSSE



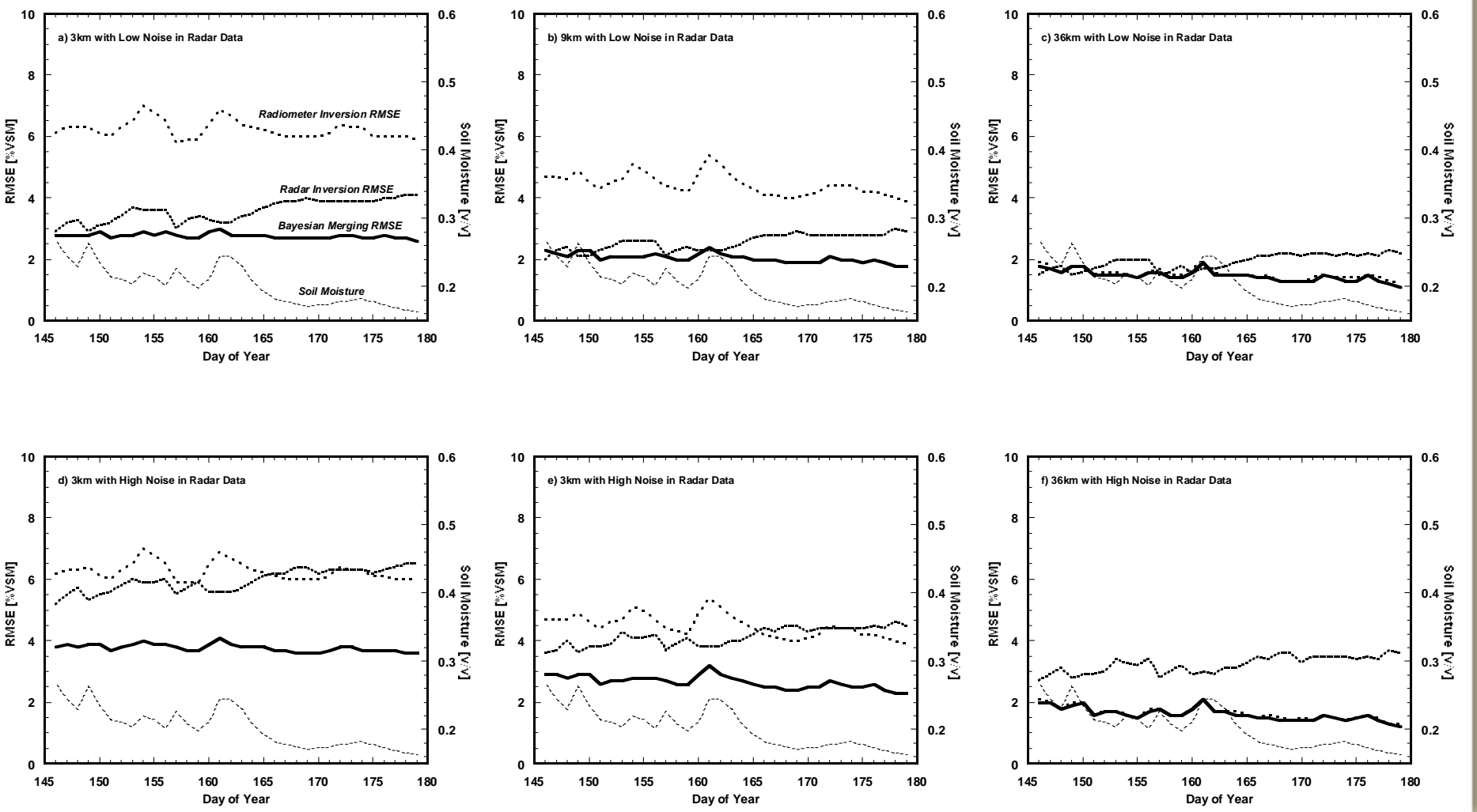
# Retrieving High Resolution Soil Moisture from Hydros



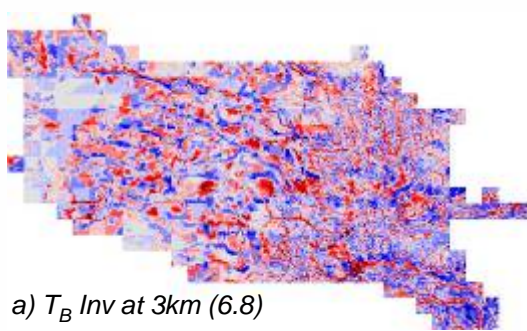
X. Zhan, P. Houser, J. Walker & W. Crow. 2006. IEEE TGRS 44(6):1534-1544



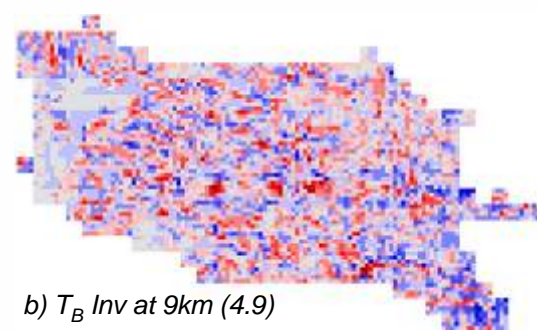
## Retrieval Error Comparison



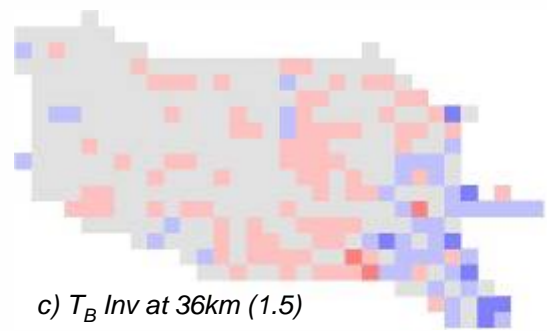
# Retrieving High Resolution Soil Moisture from Hydros



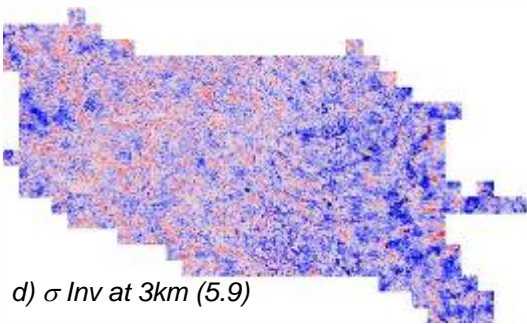
a)  $T_B$  Inv at 3km (6.8)



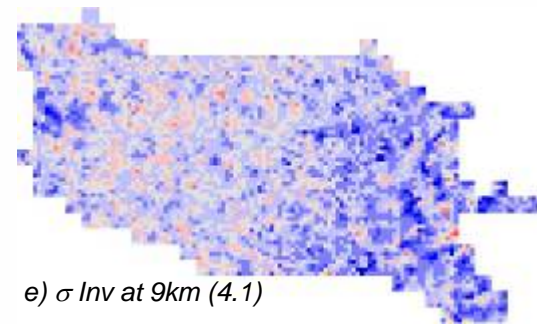
b)  $T_B$  Inv at 9km (4.9)



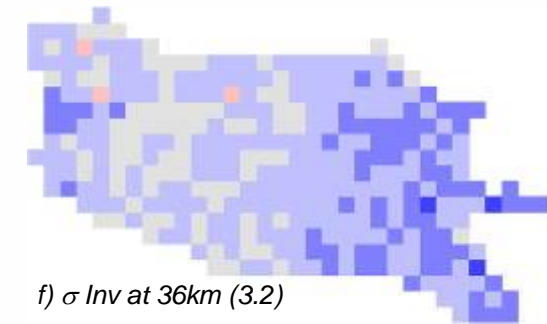
c)  $T_B$  Inv at 36km (1.5)



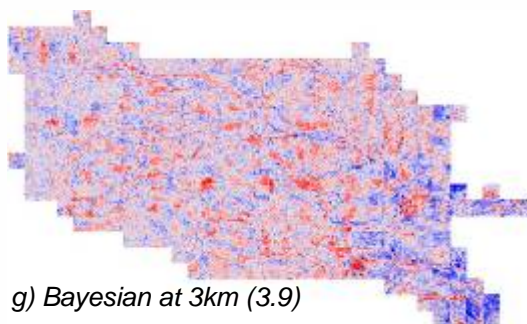
d)  $\sigma$  Inv at 3km (5.9)



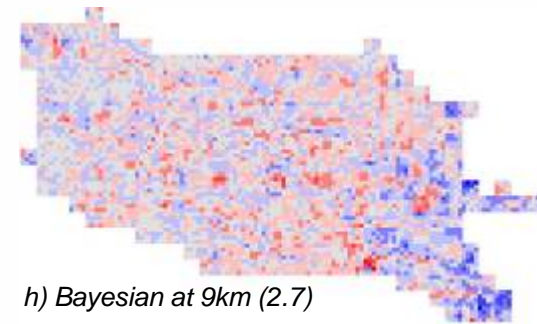
e)  $\sigma$  Inv at 9km (4.1)



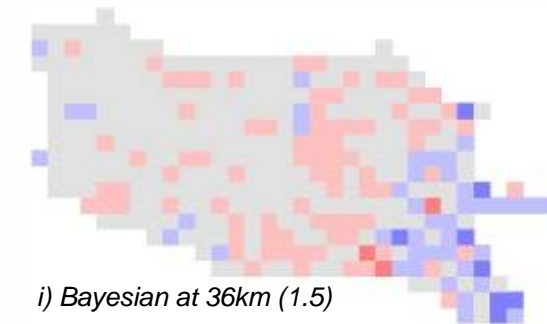
f)  $\sigma$  Inv at 36km (3.2)



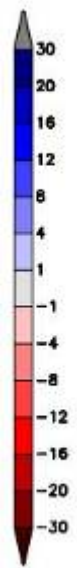
g) Bayesian at 3km (3.9)



h) Bayesian at 9km (2.7)



i) Bayesian at 36km (1.5)



## ❖ *EnKF, LIS and Soil Moisture Data Assimilation*

# Brief History of Kalman Filter Data Assimilation

- ❖ **Swerling (1958), Kalman (1960):** *Kalman Filter(KF) - a recursive solution for the discrete-data linear filtering problem. Applied in NASA's Apollo navigation computer in 1960.*
- ❖ **Schmidt (~1960):** *Applied Extended KF (EKF) to non-linear systems.*
- ❖ **Evensen (1992):** *Applied EKF for oceanic sequential data assimilation and found closure problem for error covariance propagation in EKF.*
- ❖ **Evensen(1994):** *Applied Monte Carl method for error covariance estimation in KF that lead to the Ensemble Kalman Filter (EnKF) for sequential data assimilation.*
- ❖ **Entekhabi (1994):** *Applied EKF to estimate soil temperature and moisture profile from surface observations.*
- ❖ **Walker & Houser (2001):** *Applied EKF to assimilate surface soil Moisture for providing GCM soil moisture initialization data fields.*
- ❖ **Reichle et al (2002):** *Applied EnKF for soil moisture estimation.*
- ❖ **Crow & Wood (2003):** *Used EnKF to assimilate TB observations.*
- ❖ **Zhan et al (2002), Kumar et al (2006), Zhan et al (2006):** *Implemented EKF & EnKF in LDAS/LIS for operational land data assimilation.*

- ❖ **Land Information System (LIS)** is a package of computer programs of the **Land Data Assimilation Systems (LDAS)** enhanced with object-oriented programming technology;
- ❖ LIS executes major land surface models (**Noah**, Mosaic, CLM, etc.) with unified input land surface parameter and meteorological forcing fields and standardized outputs;
- ❖ **Ensemble Kalman Filter (EnKF)** is the mostly used sequential data assimilation algorithm in hydrological research;
- ❖ EnKF is implemented in such a way that any observations of any LSM state variables can be assimilated into the LSM without much modification to the computer code.

# Land Data Assimilation Systems (LDAS)



## Inputs

## Physics

## Outputs

## Applications

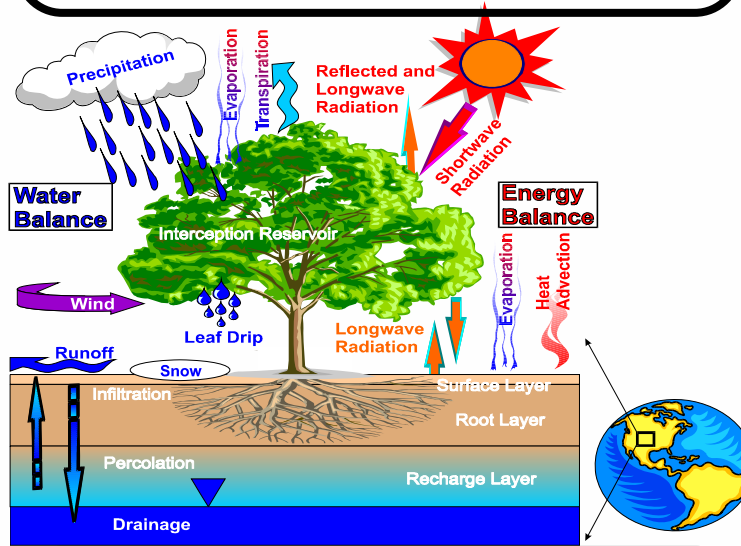
Topography,  
Soils

Land Cover,  
Vegetation  
Properties

Meteorology

Snow  
Soil Moisture  
Temperature

Land Surface Models



Soil  
Moisture &  
Temperature

Evaporation

Runoff

Snowpack  
Properties

Weather/  
Climate

Water  
Resources

Homeland  
Security

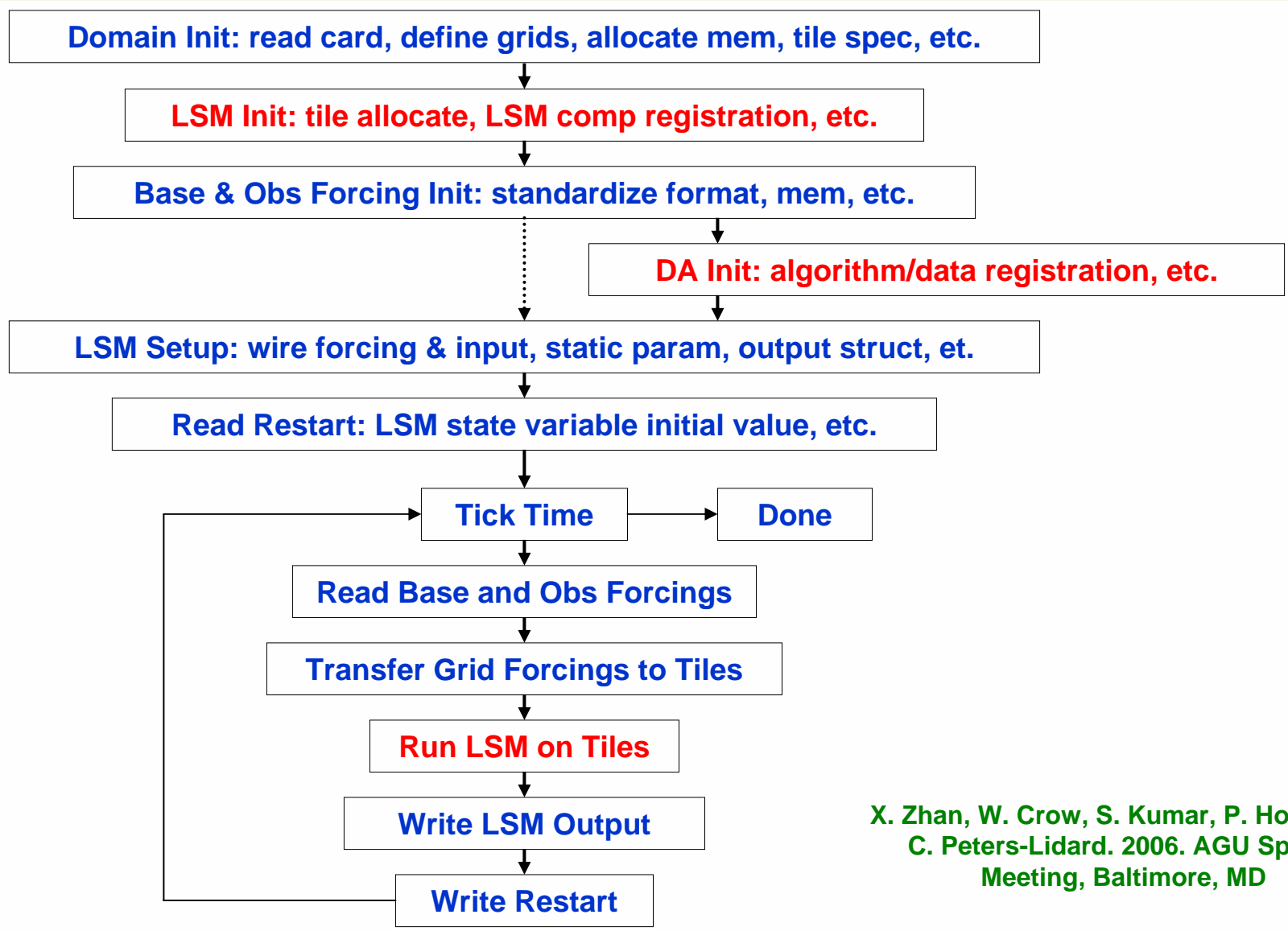
Military  
Ops

Natural  
Hazards

Data Assimilation Modules



# Implementation of Kalman Filters in LIS



X. Zhan, W. Crow, S. Kumar, P. Houser, & C. Peters-Lidard. 2006. AGU Spring Meeting, Baltimore, MD

## &data\_assimilation

```
LIS%a%DAALG = 3 ! 0-no,1-di,2-ekf,3-enkf da method
LIS%a%DAOBS = 2 ! 0-no,1-tmi_sm,2-syn_sm,3-amsre_sm, ...
LIS%a%DAVAR = 1 ! 0-no,1-sm,2-ts,
LIS%a%NSTV = 16 ! # of LSM state variables
LIS%a%NDAV = 4 ! # of prog model vars to be assimilated
LIS%a%NENS = 10 ! number of ensemble members for EnKF
LIS%a%RENSEM= 0 ! write ensembler data into files (0-n,1-y)
LIS%a%fvlfm = "./data/perturb/f_mos.dat" ! forc perturb'ns
LIS%a%svlfm = "./data/perturb/s_mos.dat" ! stat perturb'ns
/
```

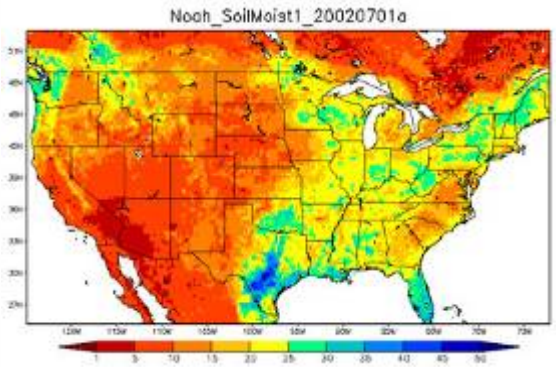
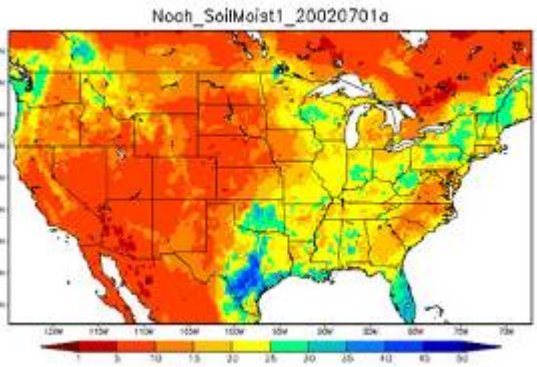
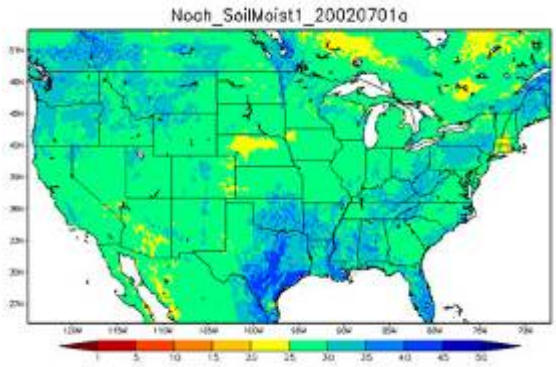
## &soil\_moisture\_da

```
smobsdir = "./data/NOAHSoilMoist1_NLDAS" ! data location
nob      = 1      ! # of obs vars (e.g. surface sm)
oer      = 0.01   ! obs error rate
Mer      = 0.03   ! Mdl error rate
/
```

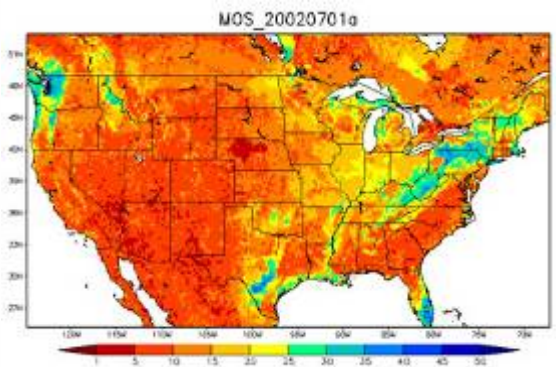
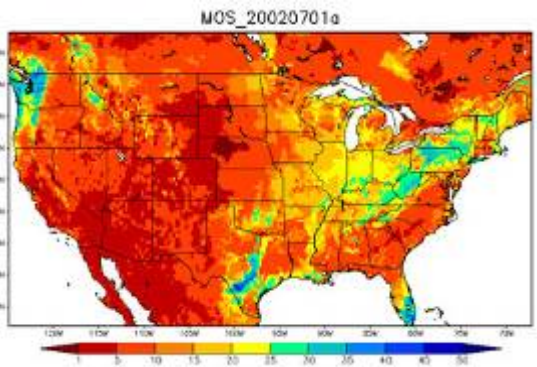
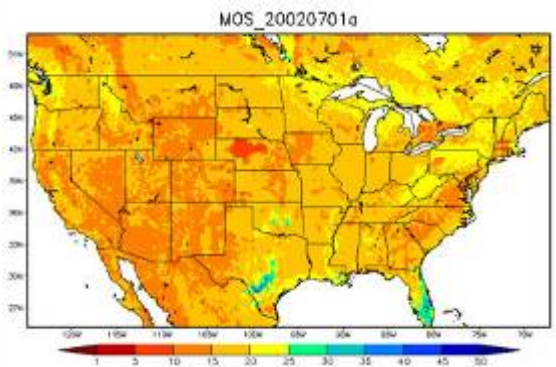
# EnKF Assimilation of Synthetic SM Data in LIS

## Test LIS-KF with Synthetic SM Data

Noah



Mosaic



LSM Run

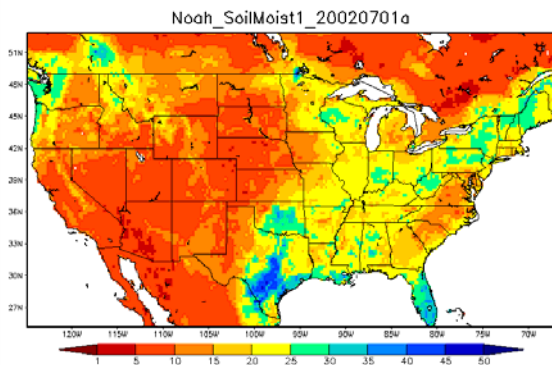
Synthetic Obs

EnKF Assimilation

X. Zhan, W. Crow, S. Kumar, P. Houser, & C. Peters-Lidard. 2006. AGU Spring Meeting, Baltimore, MD

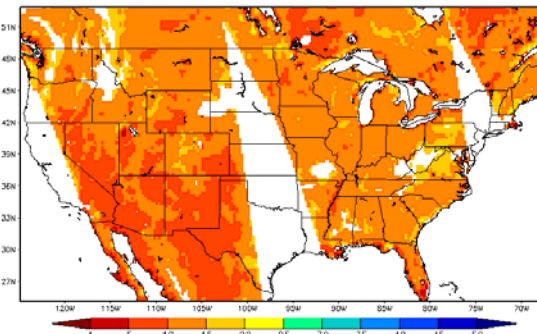
## Test LIS-KF with AMSR-E SM Data

### Noah LSM Run



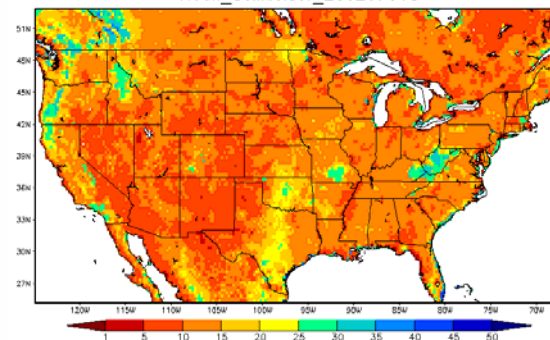
### AMSR-E SM

AMSR-E SM 20020701a



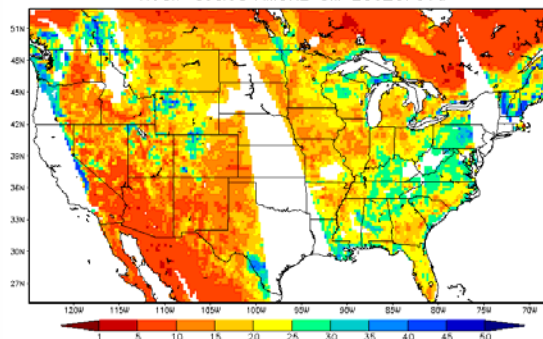
### EnKF Assimilation

Noah\_SoilMoist1\_20020701a



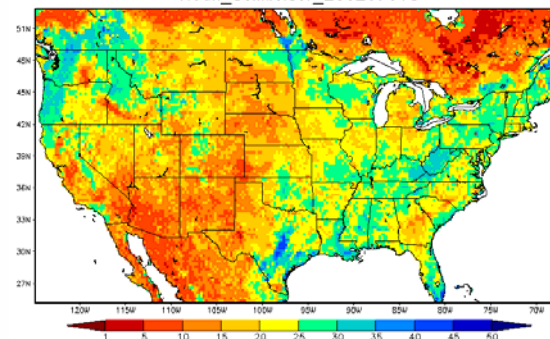
### Scaled AMSR-E

Noah-scaled AMSRE SM 20020701a



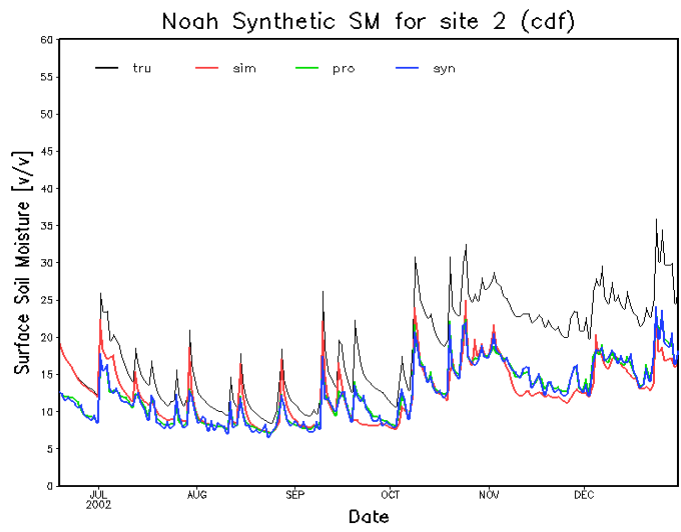
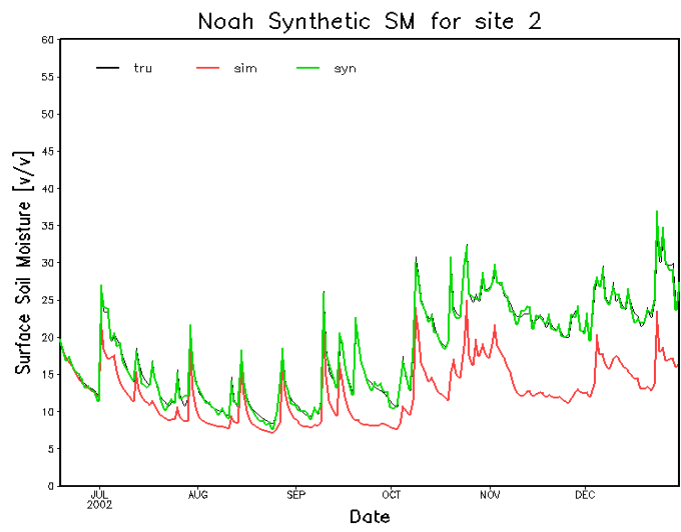
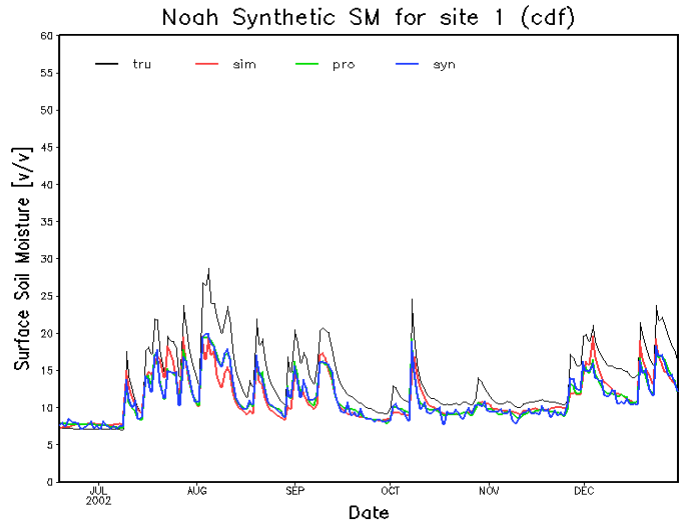
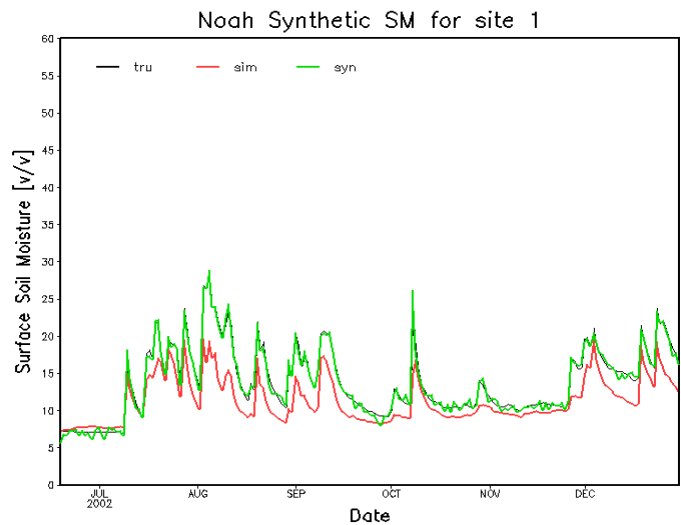
### EnKF Assimilation

Noah\_SoilMoist1\_20020701a



X. Zhan, W. Crow, S. Kumar, P. Houser, & C. Peters-Lidard. 2006. AGU Spring Meeting, Baltimore, MD

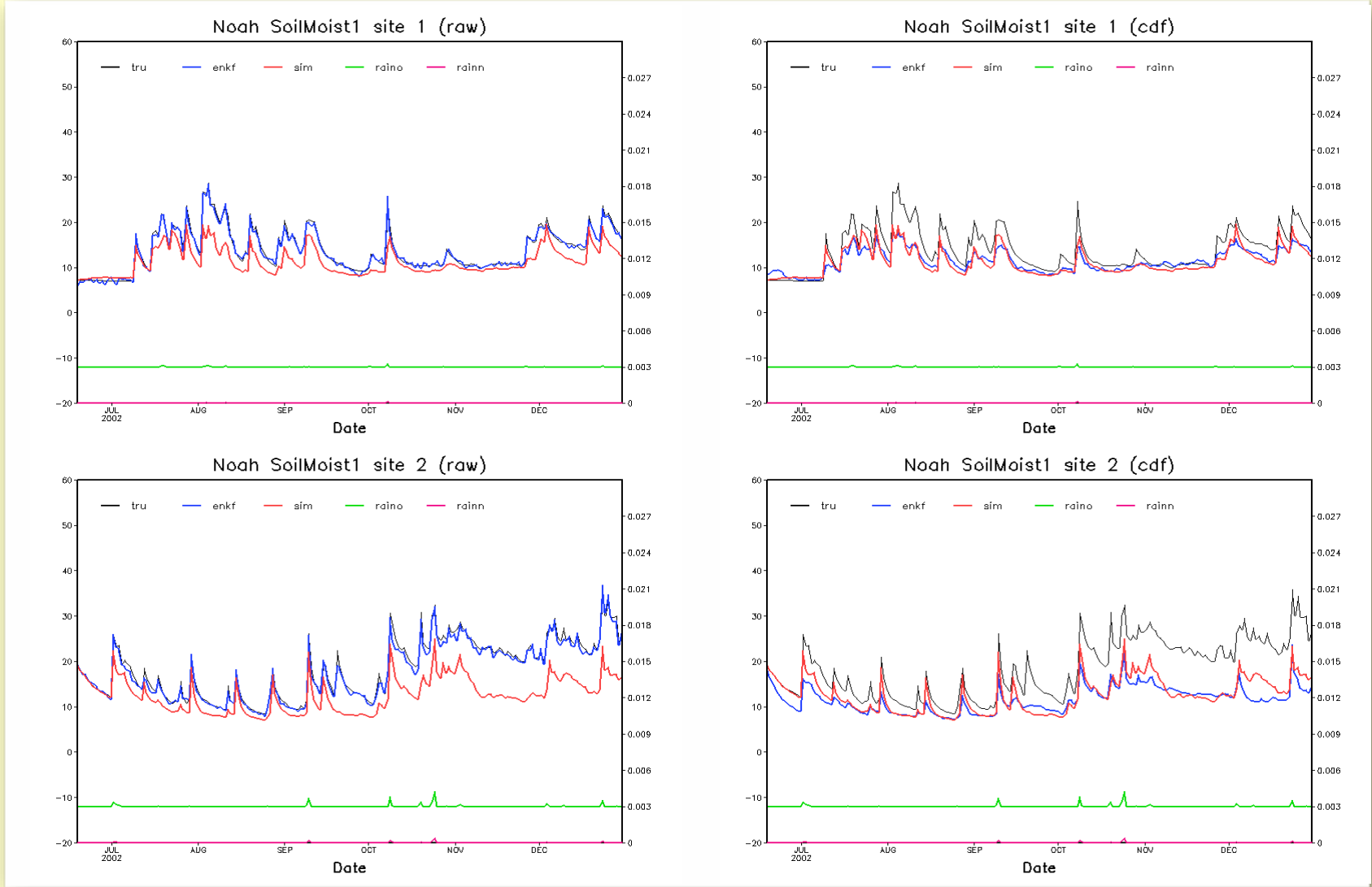
## CDF Matching Impact with Synthetic SM Data



Zhan, X., et al.  
2007. AMS  
Annual Meeting,  
San Antonio, TX

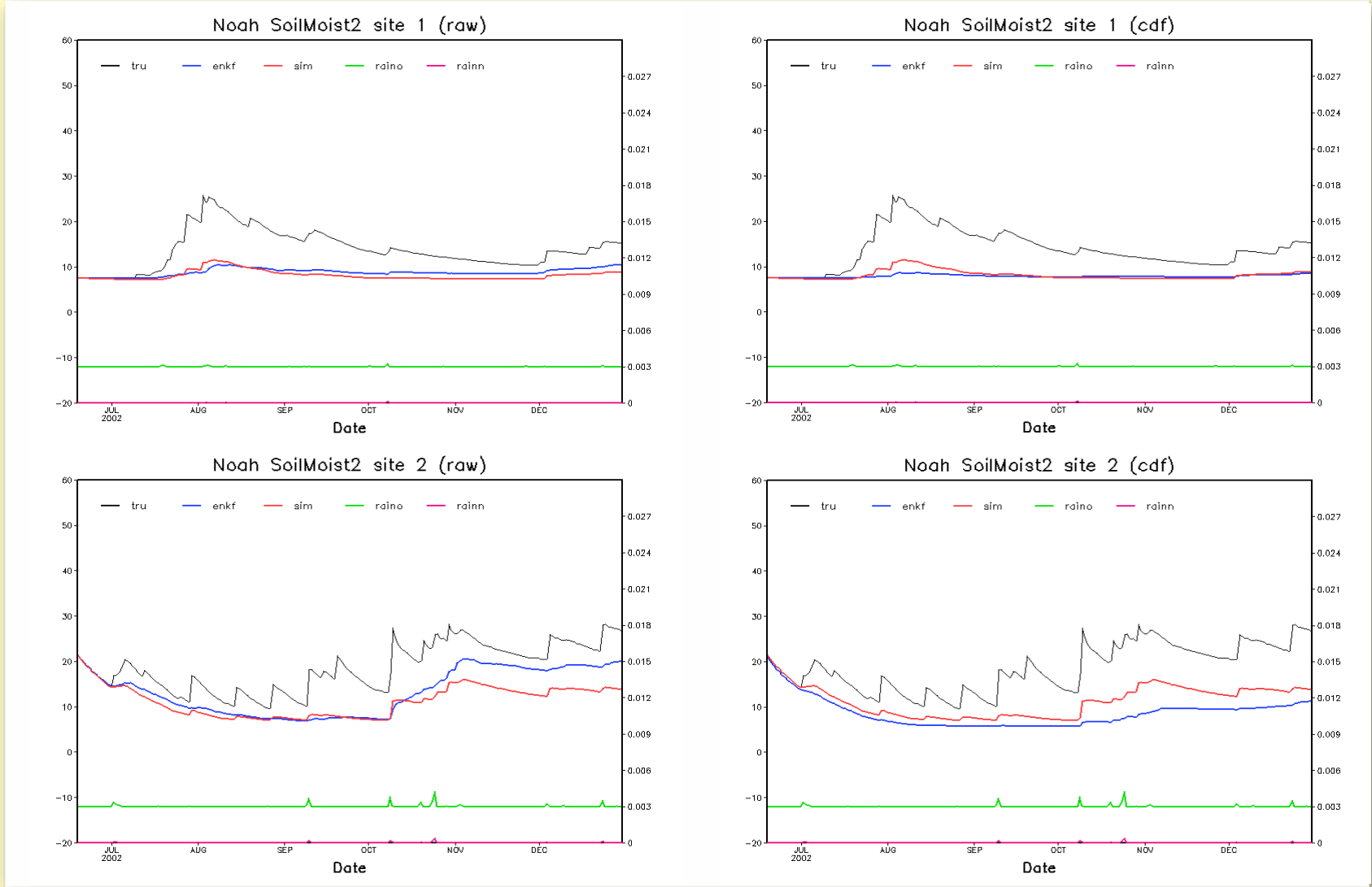


## CDF Matching Impact on EnKF DA (1)



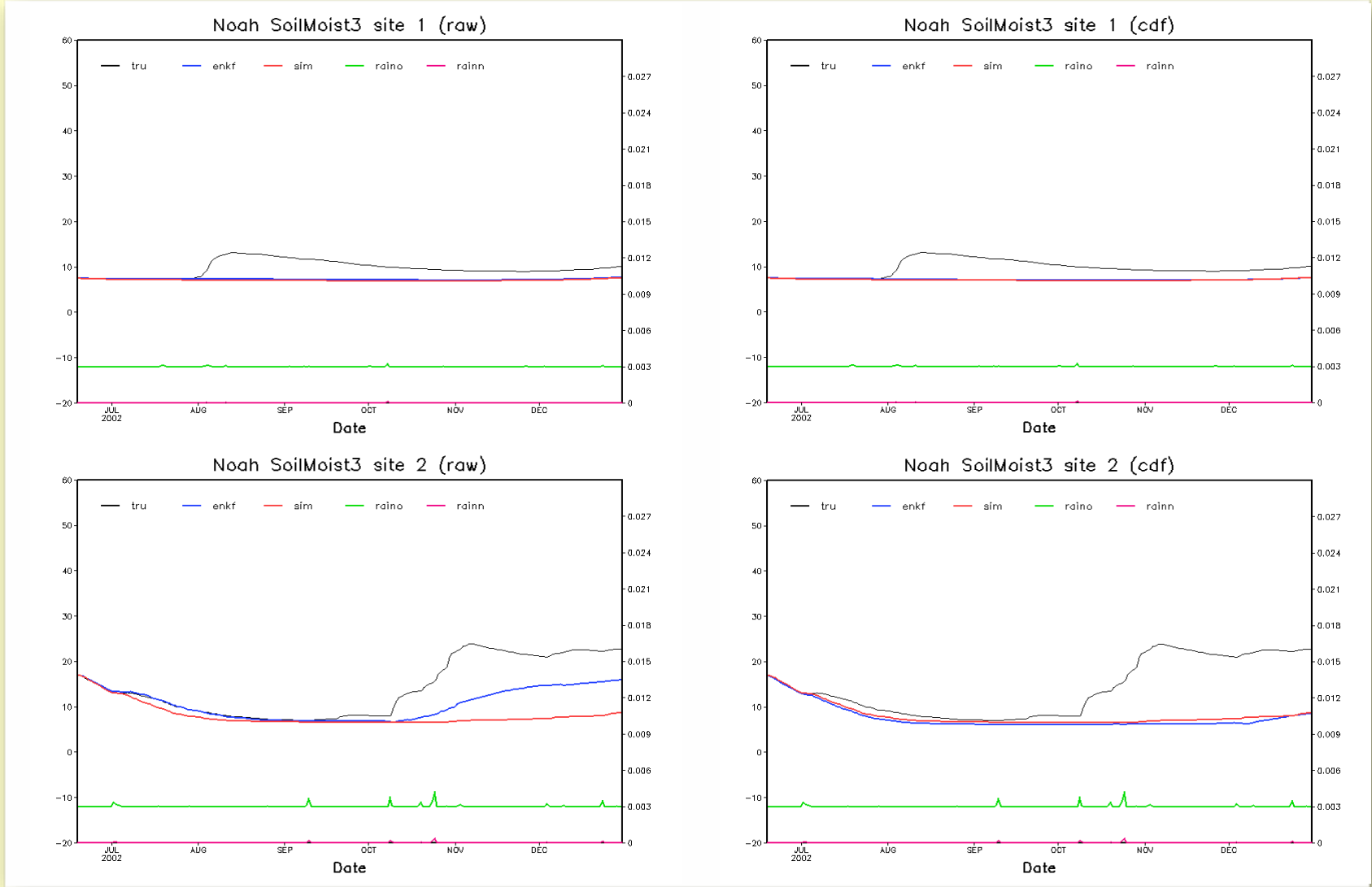


## CDF Matching Impact on EnKF DA (2)





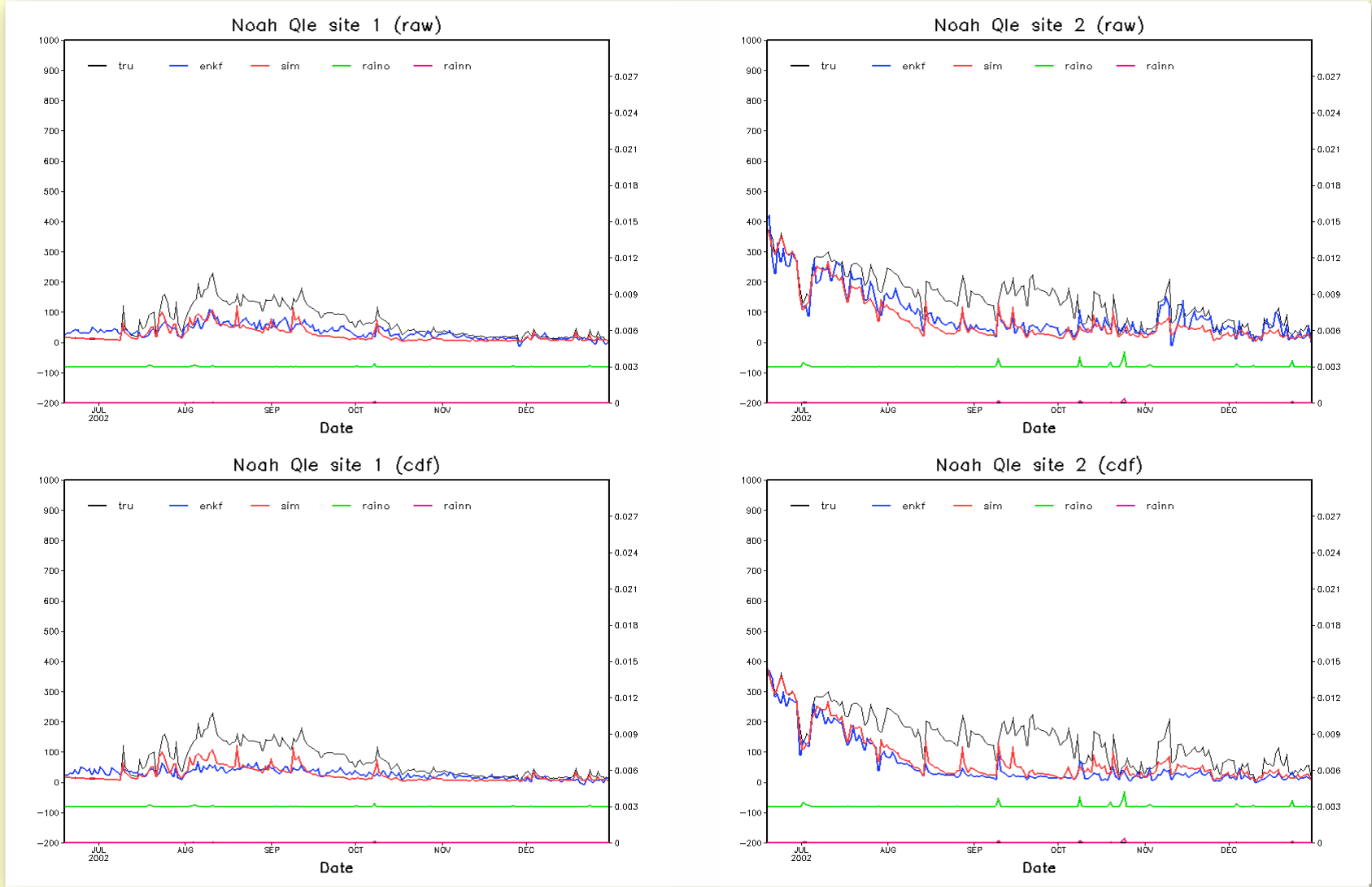
## CDF Matching Impact on EnKF DA (3)



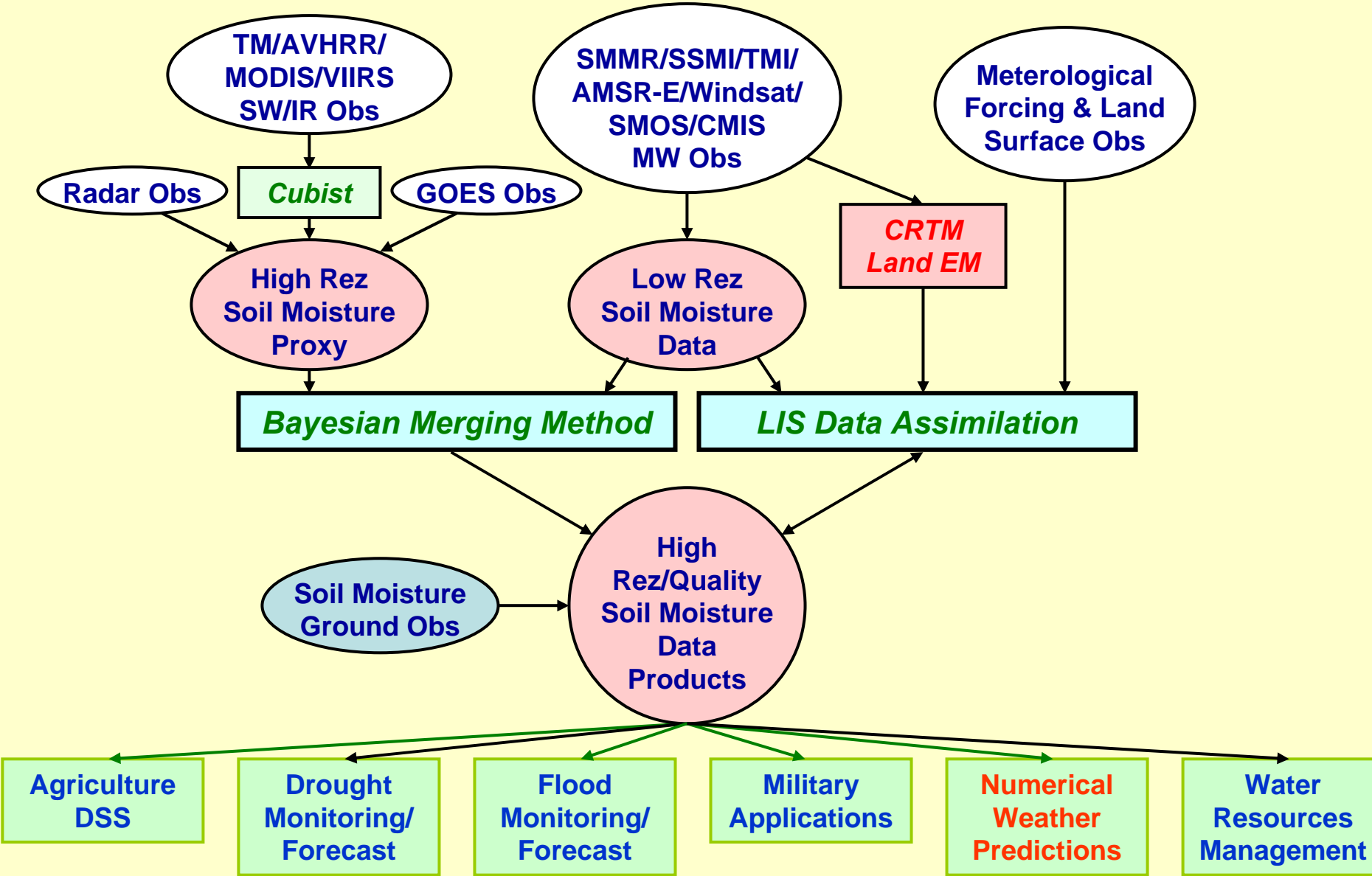




## CDF Matching Impact on EnKF DA (4)



# SM Data Research Plan





# SUMMARY

**1. SM Data & Importance :**

**2. SM Observation Techniques**

**3. MW Soil Moisture Retrievals**

**4. Soil Moisture Data Assimilation**

**5. SM Data Research Plan**

**Many research opportunities exist to improve accuracy and resolution of soil moisture data products and to broad their applications.**

*The END*

